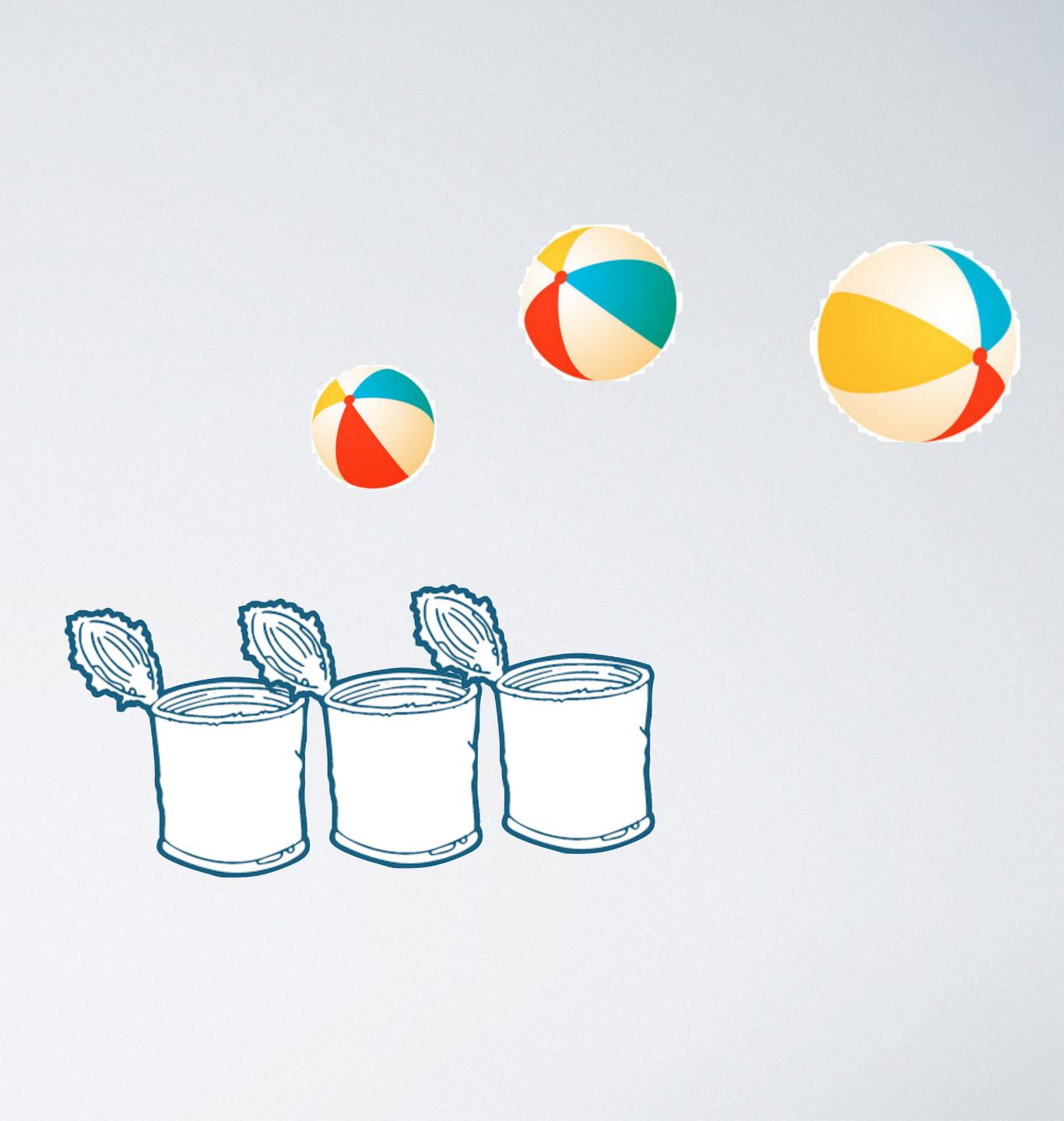
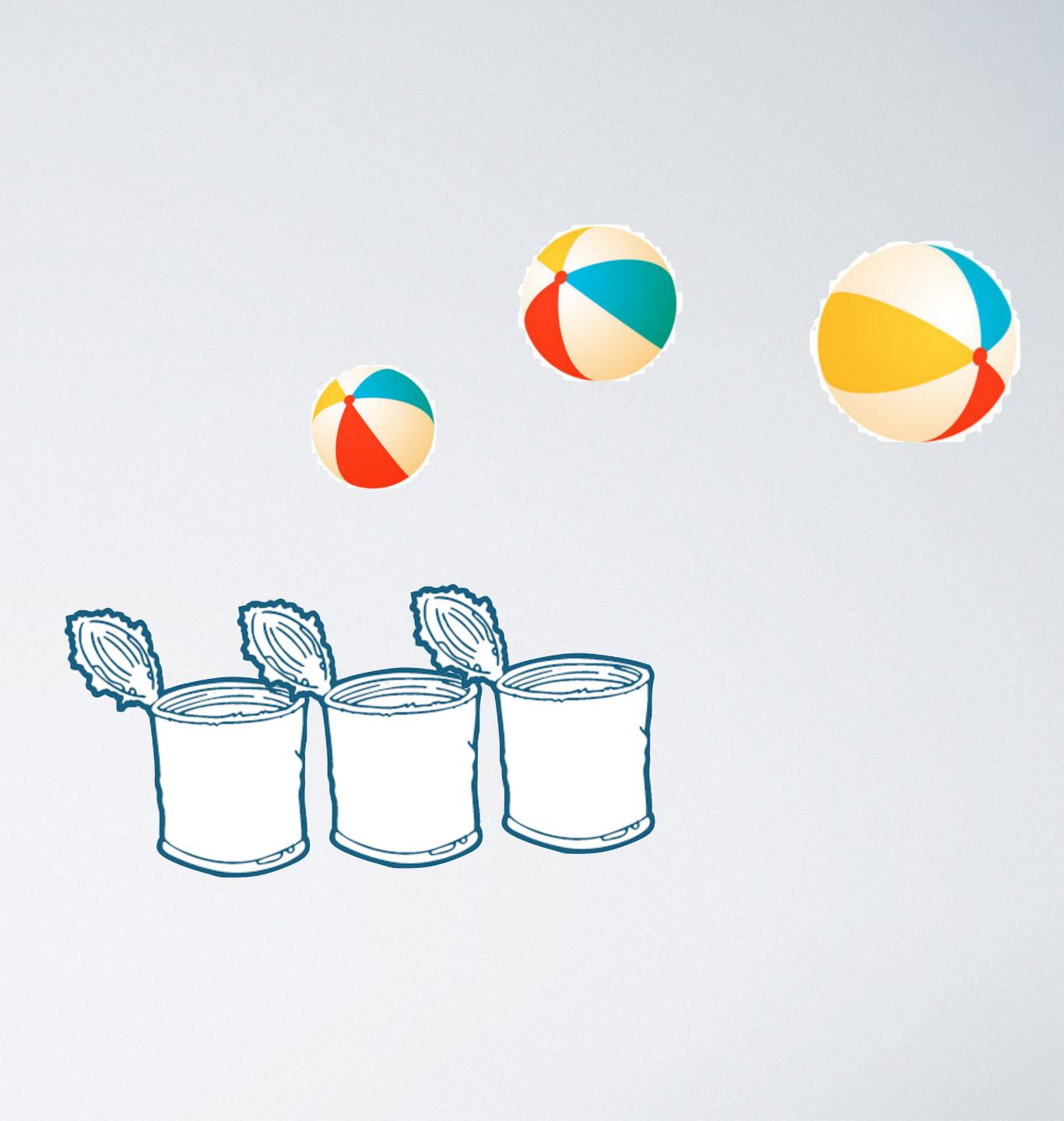
A SEPARATION LOGIC FOR NEGATIVE DEPENDENCE

Jialu Bao at PLDG, Oct. 6, 2021 Joint work with Marco Gaboardi, Justin Hsu, Joseph Tassarotti



Bad events: collision, overflow, ...



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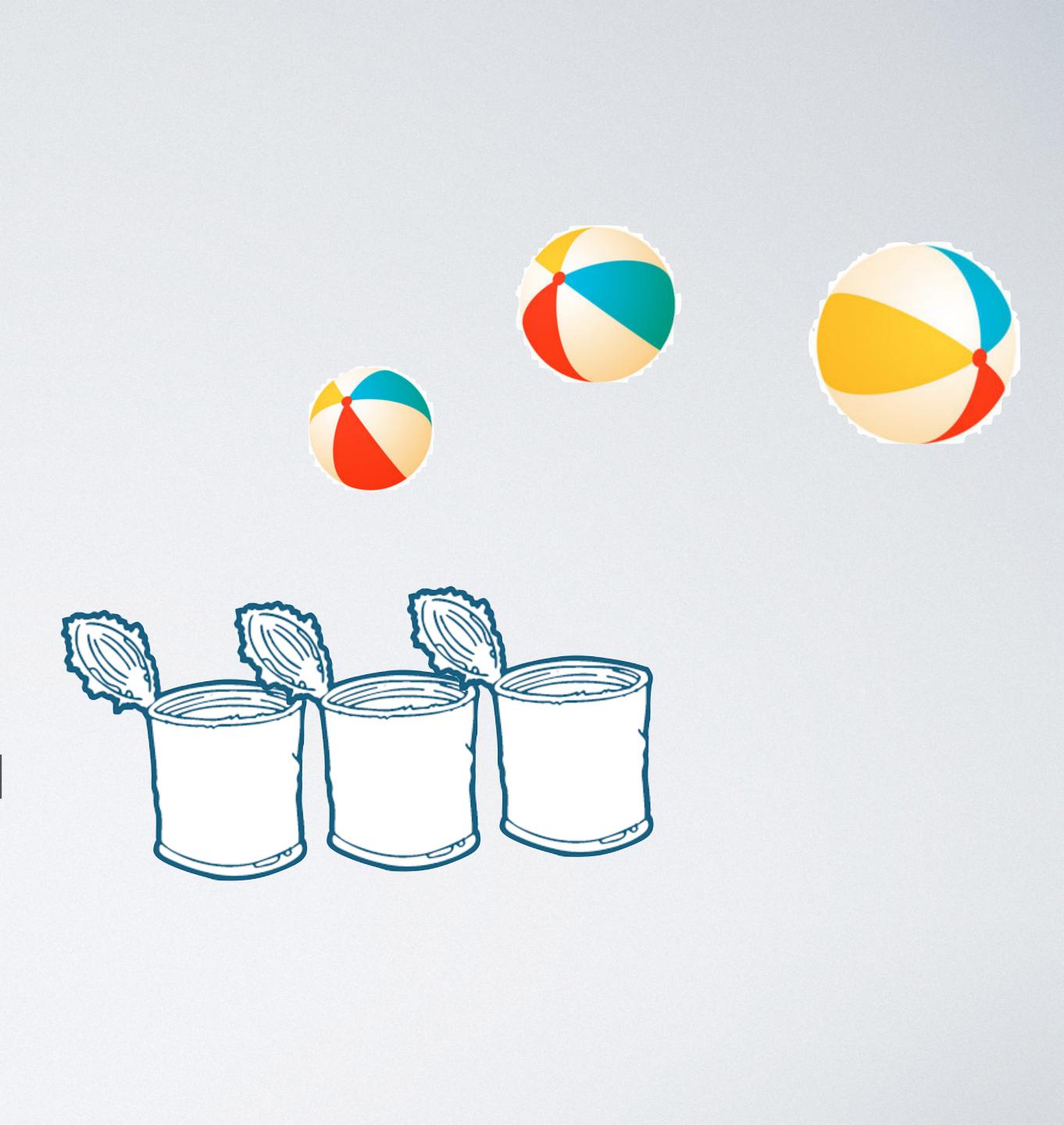
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$$\frac{Prob}{\sum_{i} \text{overflow}[i] \ge 1}_{i} \le ?$$



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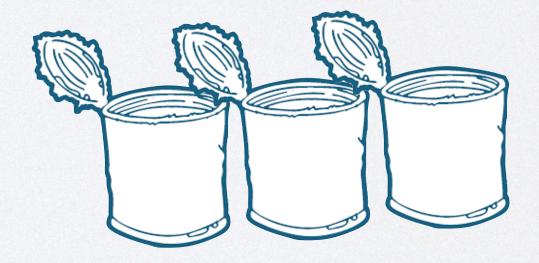


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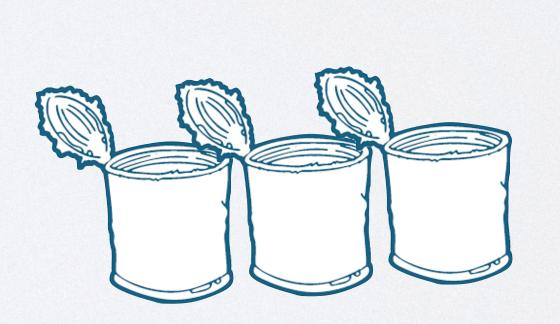


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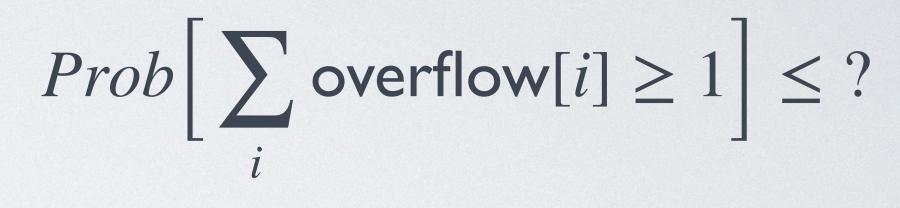




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How to prove negative dependence formally?









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Our Contribution

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- A program logic for proving negative dependence
 - Extending probabilistic separation logic [Barthe et al. 2020]

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- Show its applications to various probabilistic data structure
 - Bloom filter [Bloom 1970]
 - Permutation Hashing [Ding and König 2011]
 - Fully-dynamic dictionary [Bercea and Even 2019]
 - Repeated balls-into-bins [Becchetti et al. 2019]

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NEGATIVE DEPENDENCE

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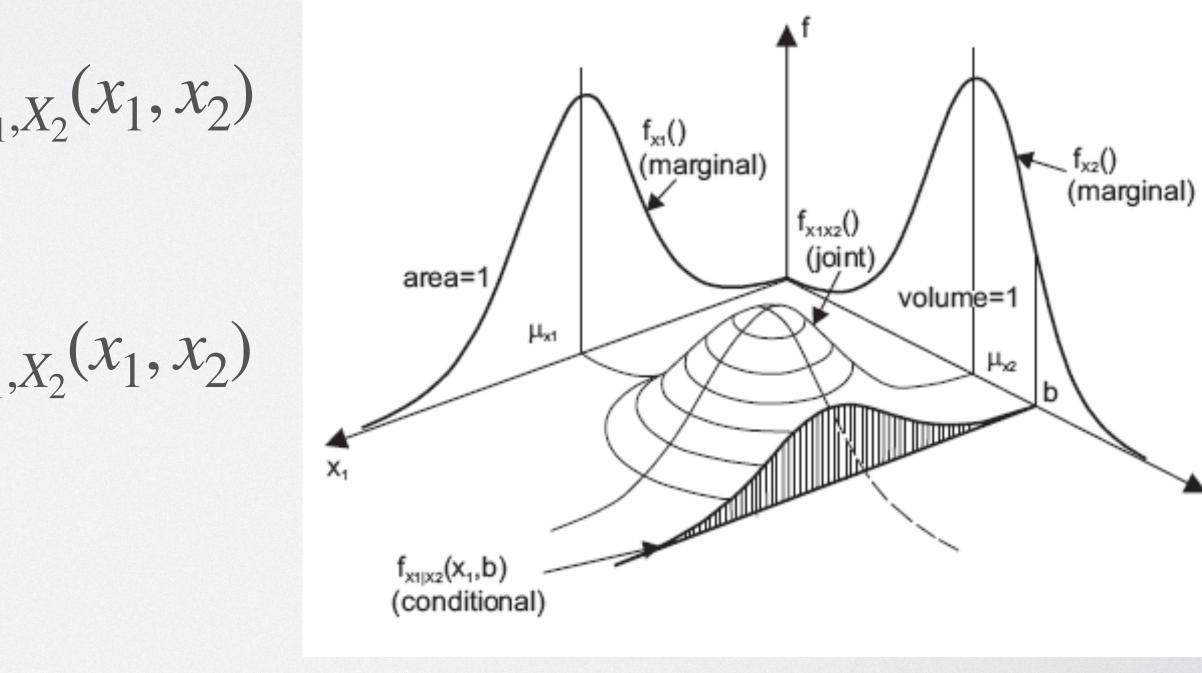
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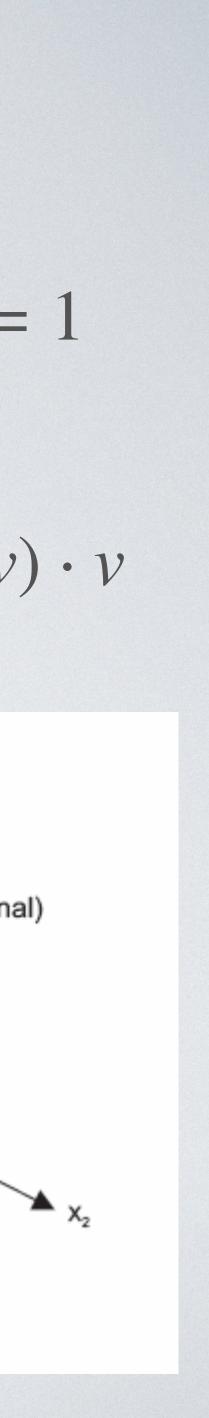
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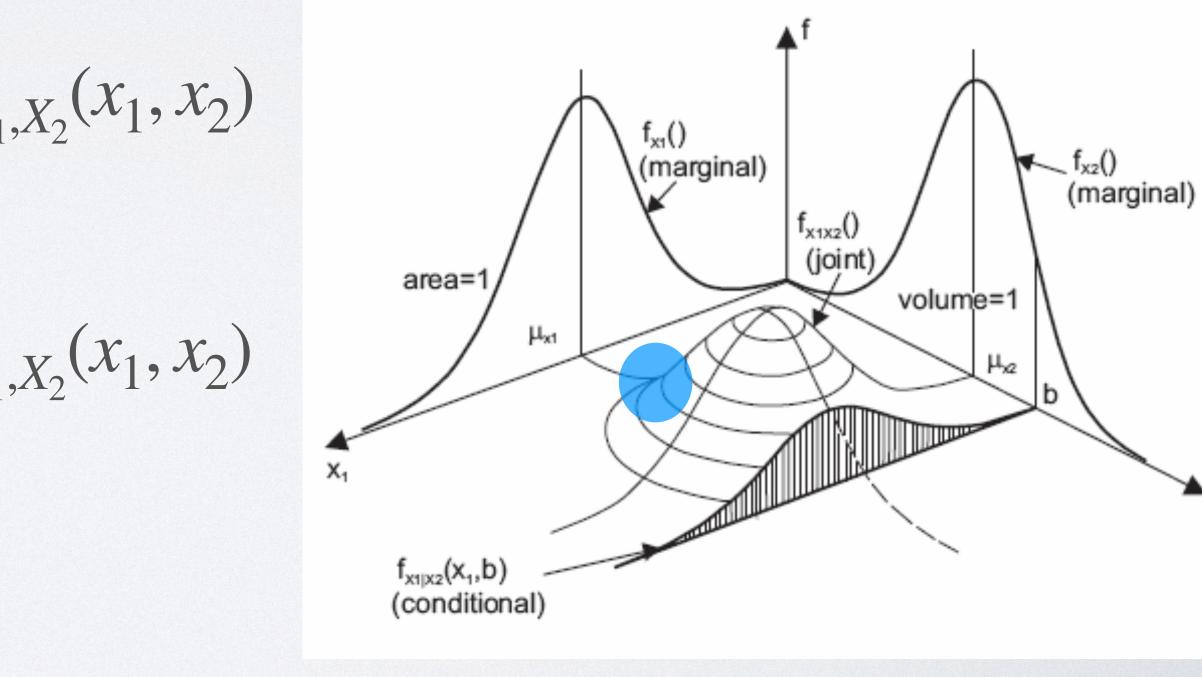


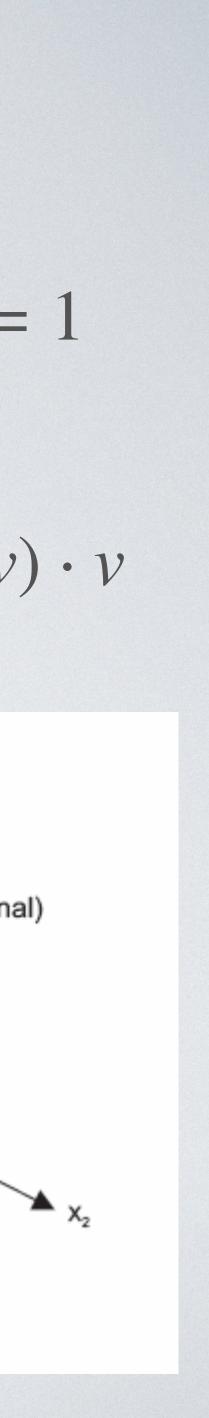
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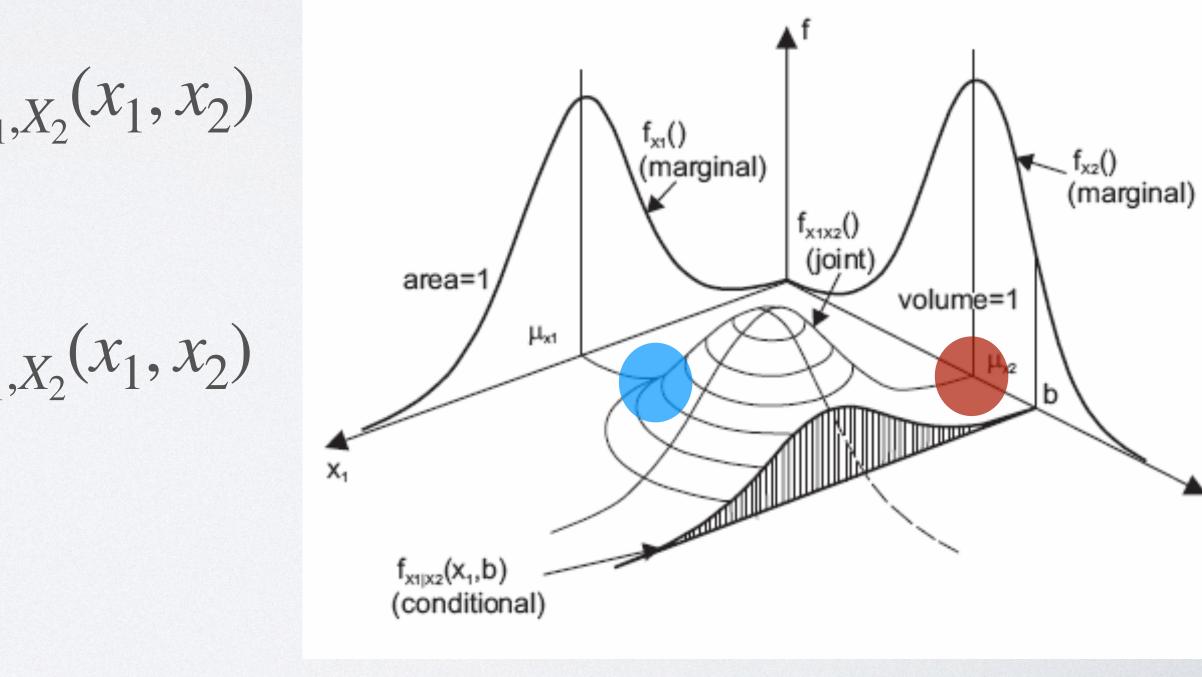


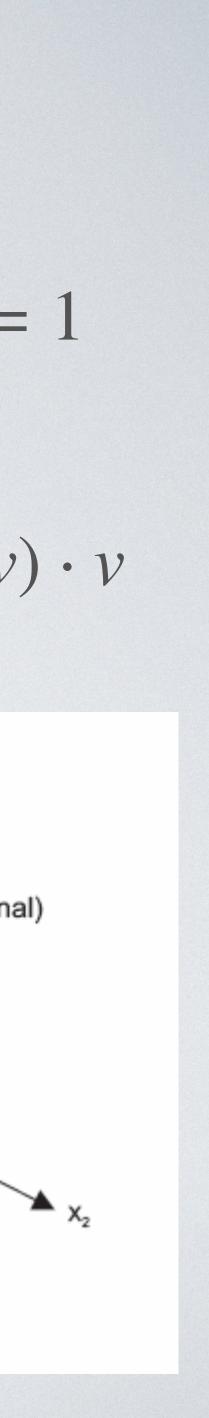
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Negative Dependence

Negative Covariance

Negative Association (NA)

Negative Quadrant Dependence

Negative Dependence

Negative Regression

- Negative Right Orthant Dependence

Negative Association





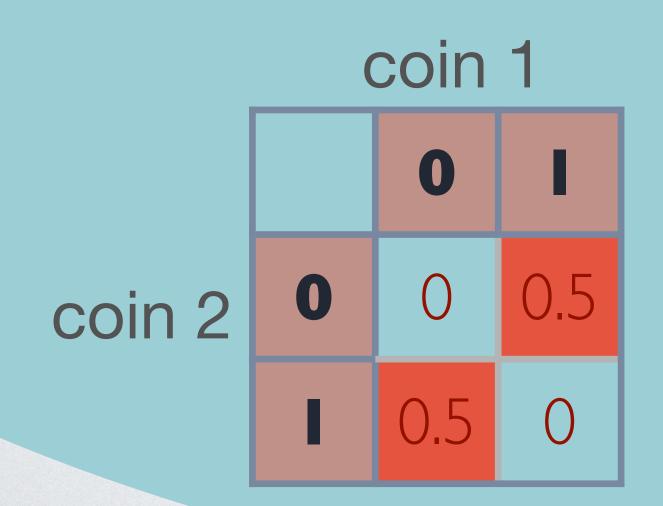
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Negative Association





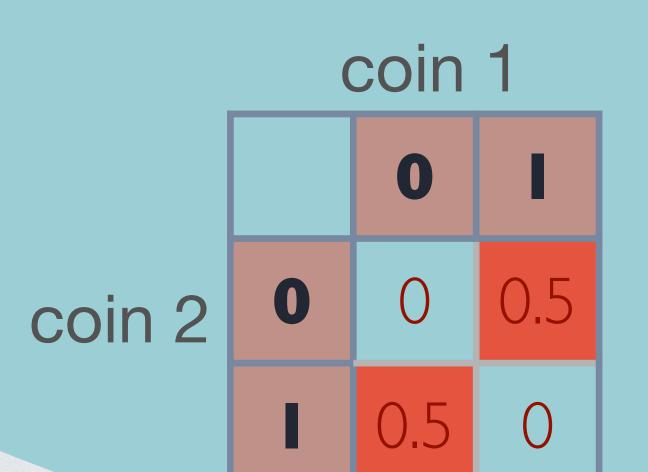
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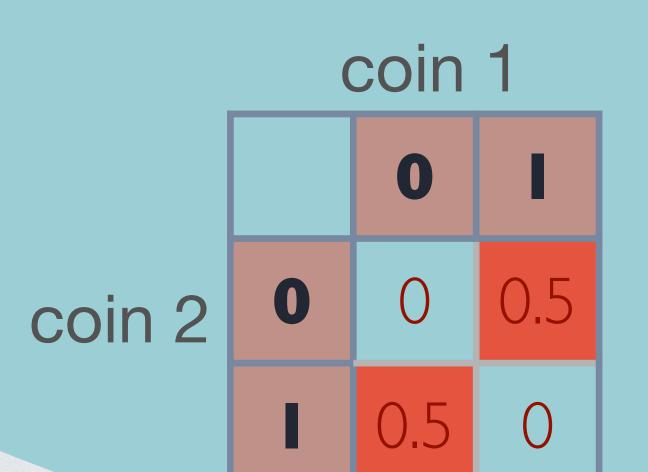


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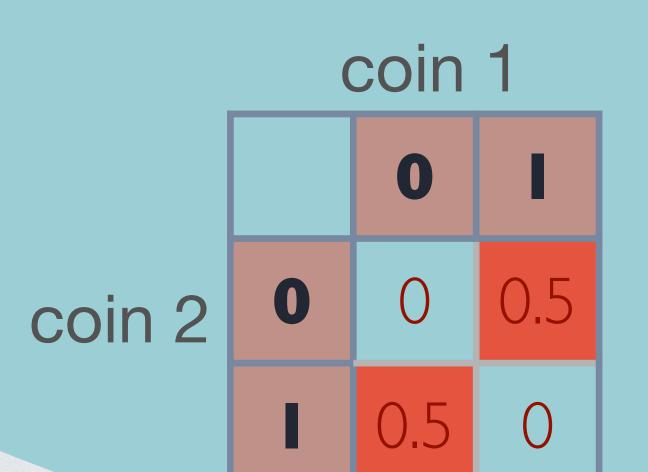
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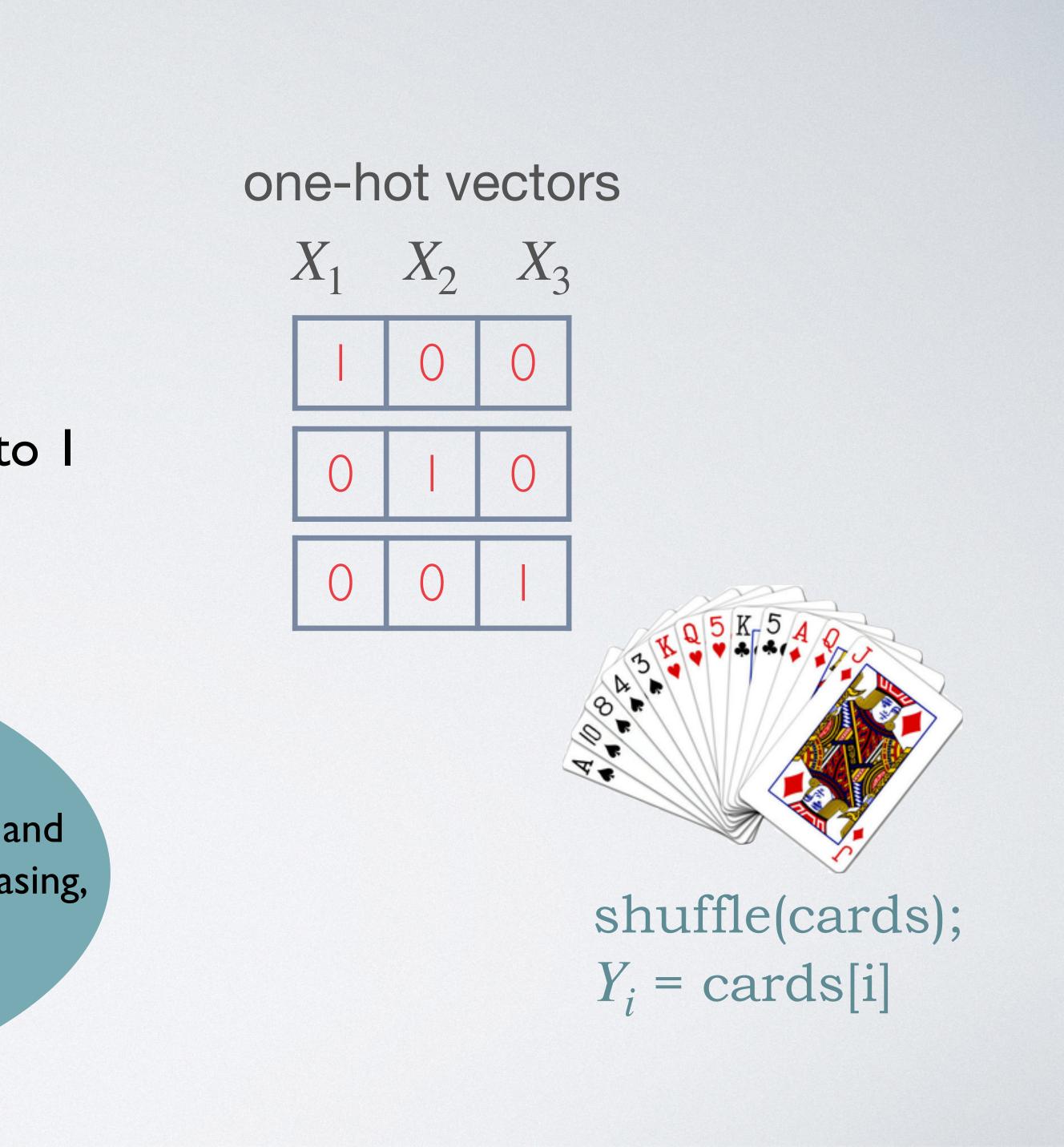
one-hot vectors $X_1 \quad X_2 \quad X_3$ () \bigcirc $\left(\right)$ ()

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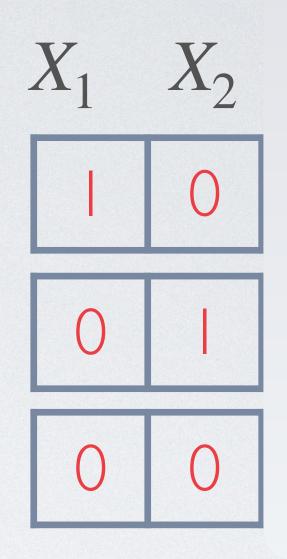
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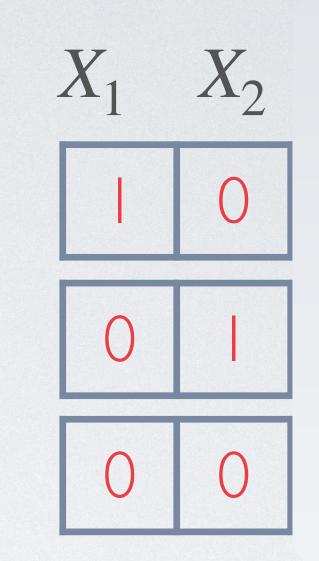


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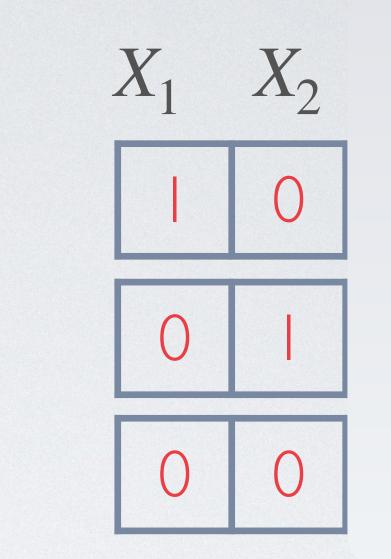


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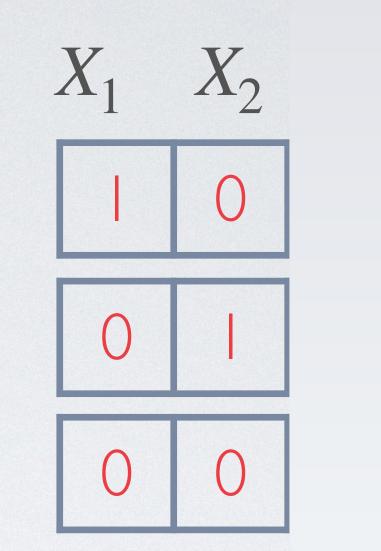
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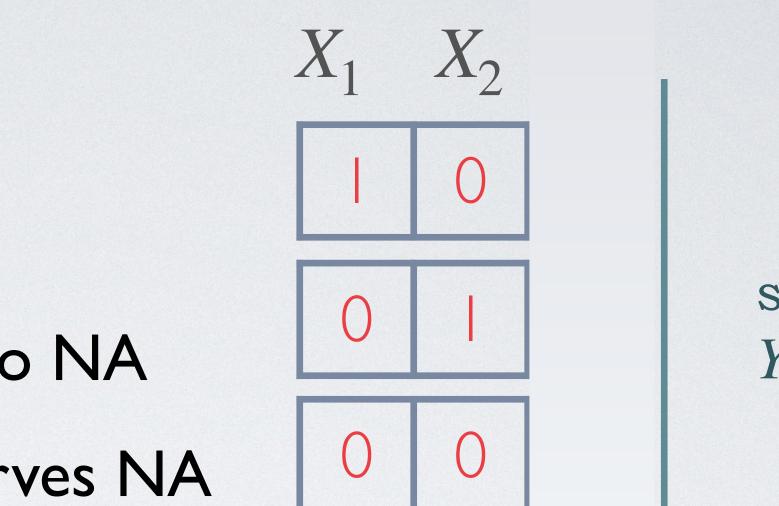


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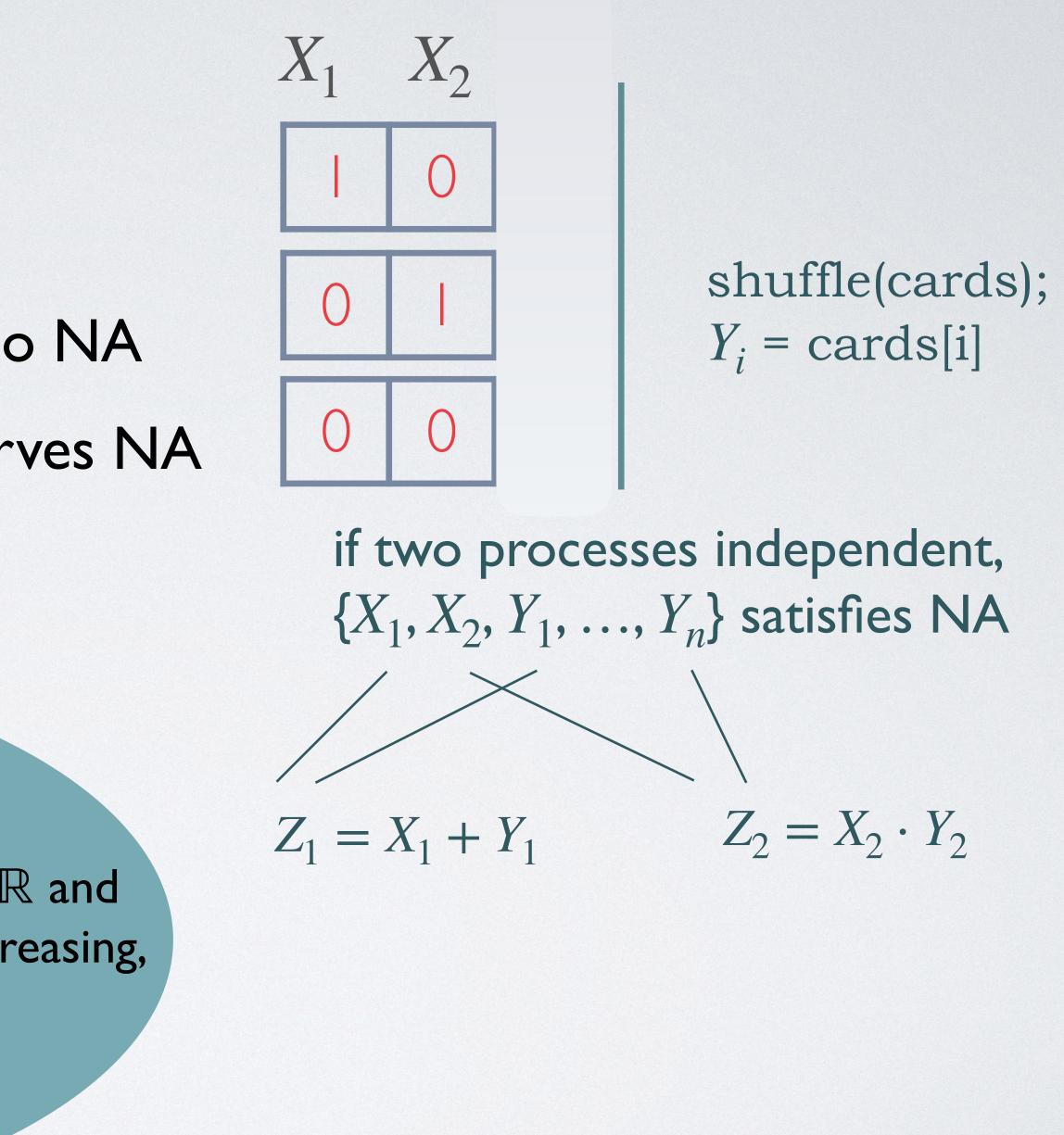
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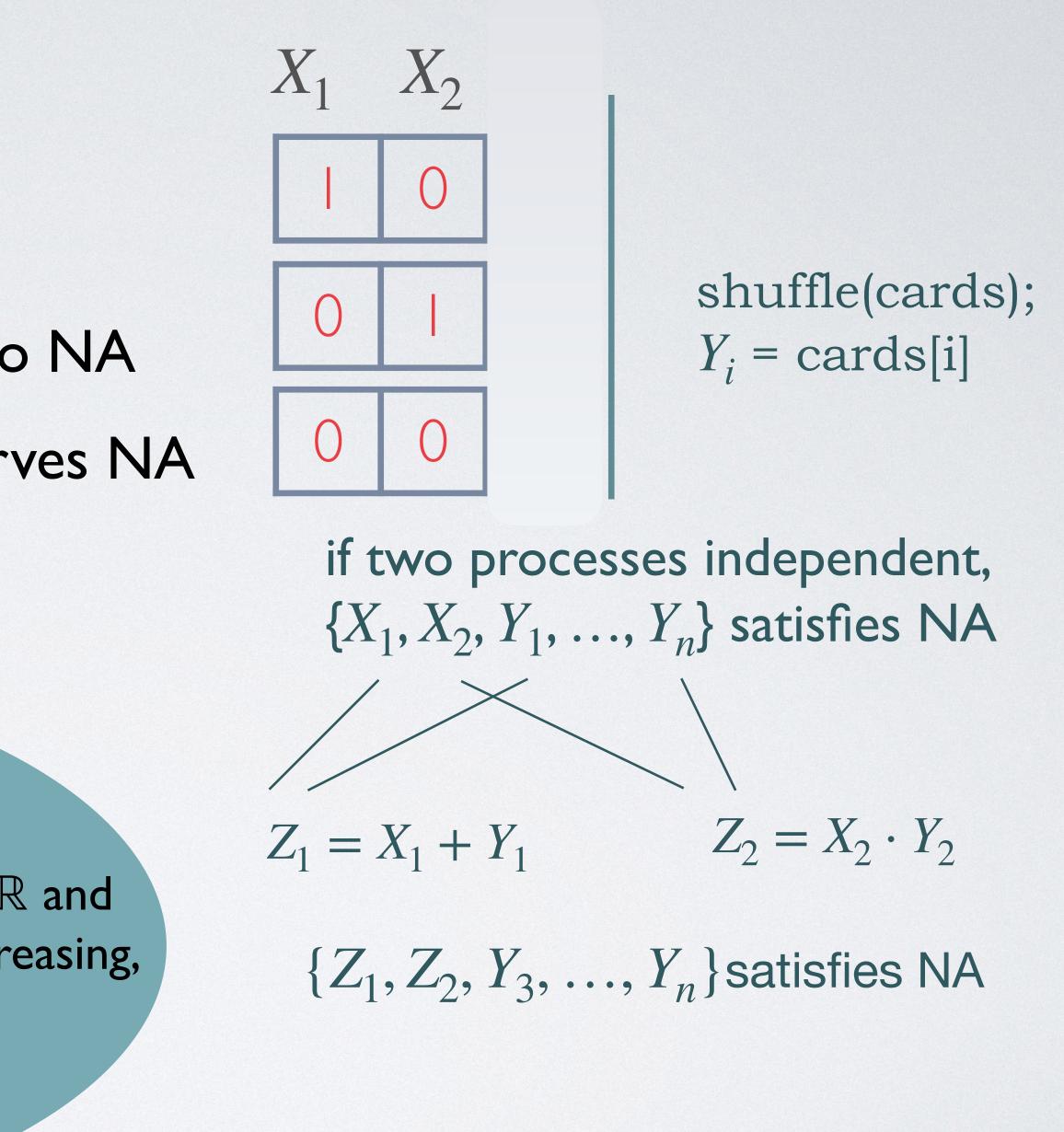
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Inductive Hypothesis

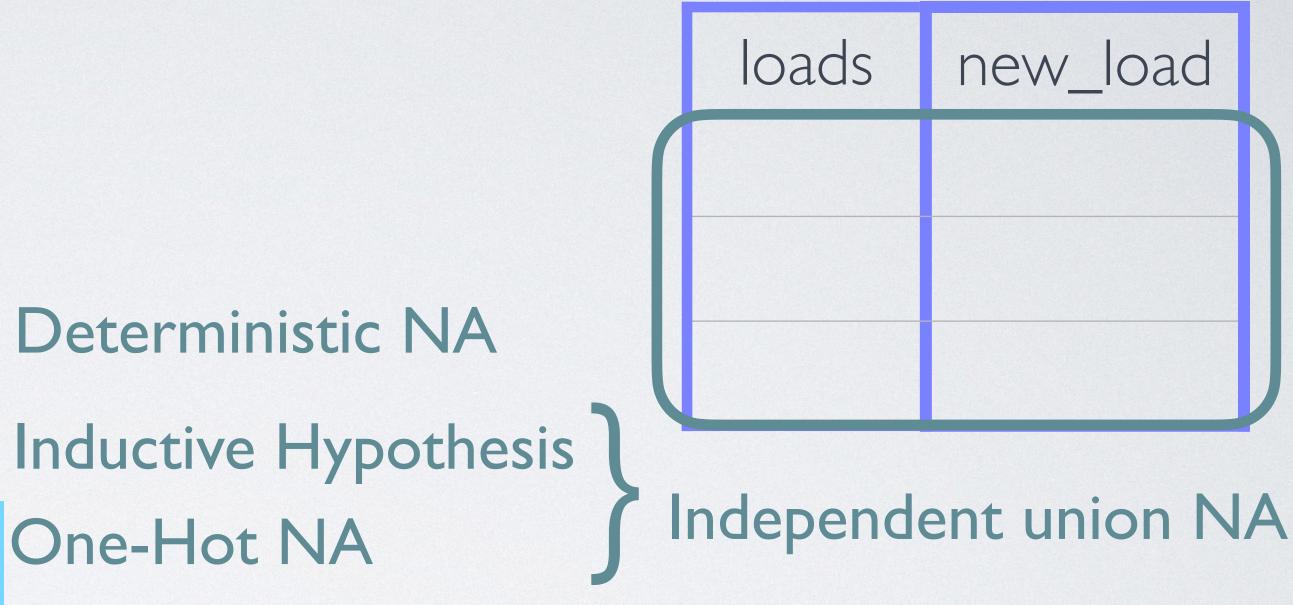
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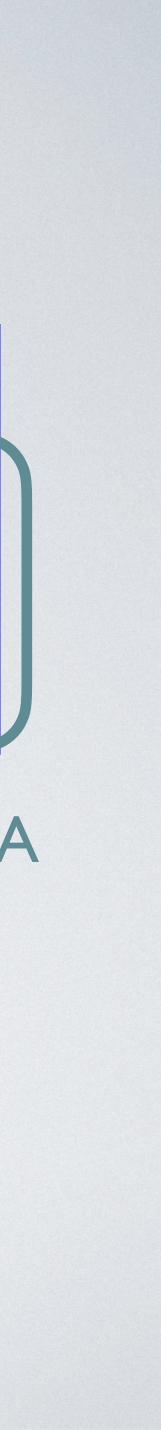
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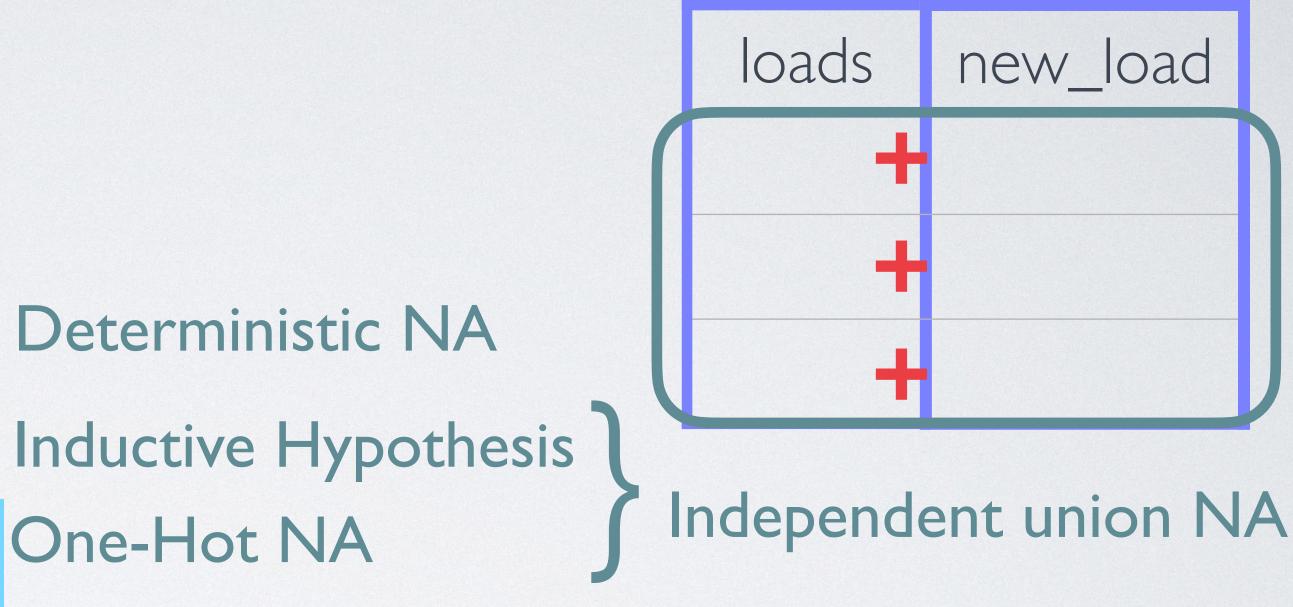
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loads

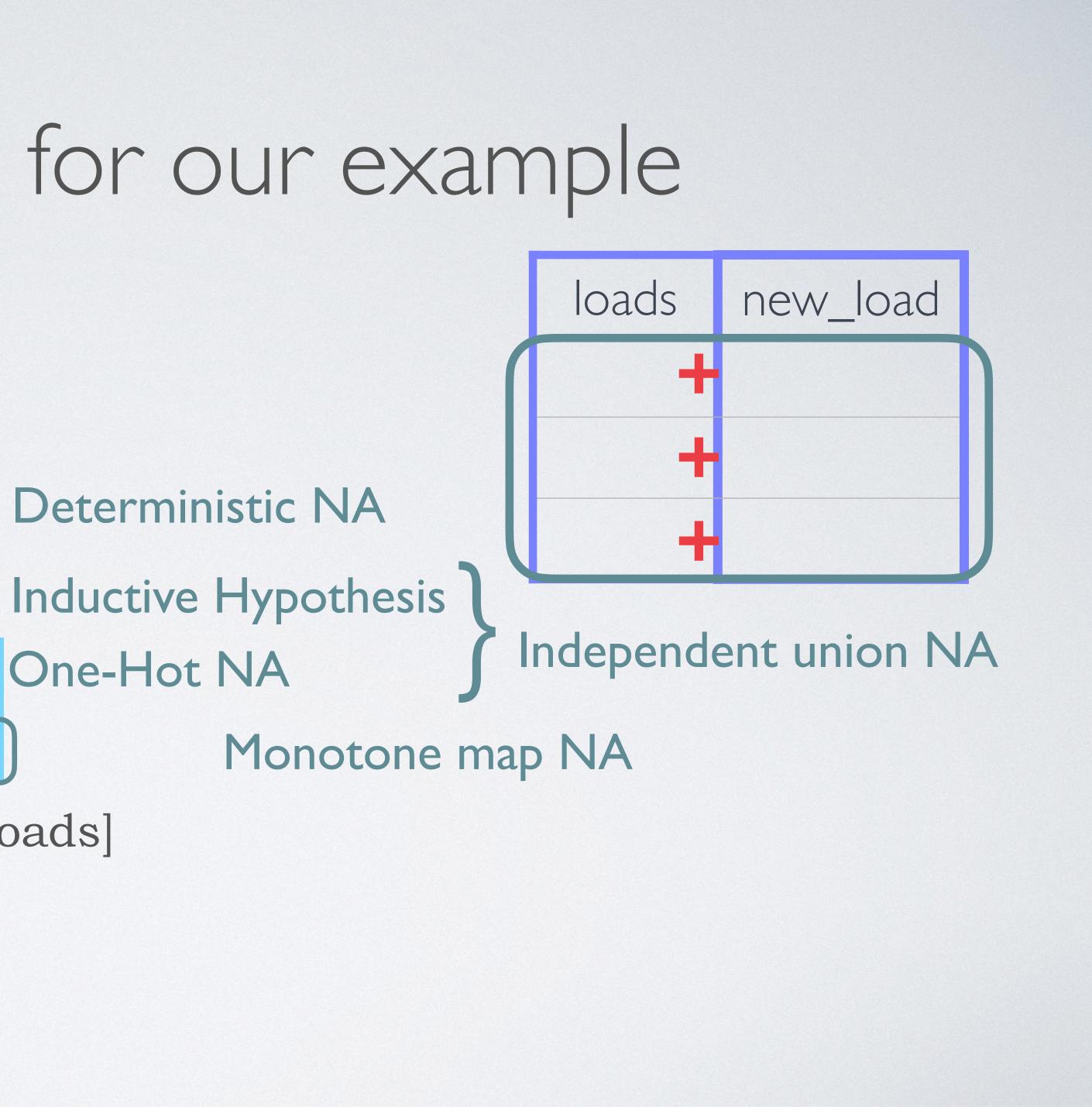
new_load

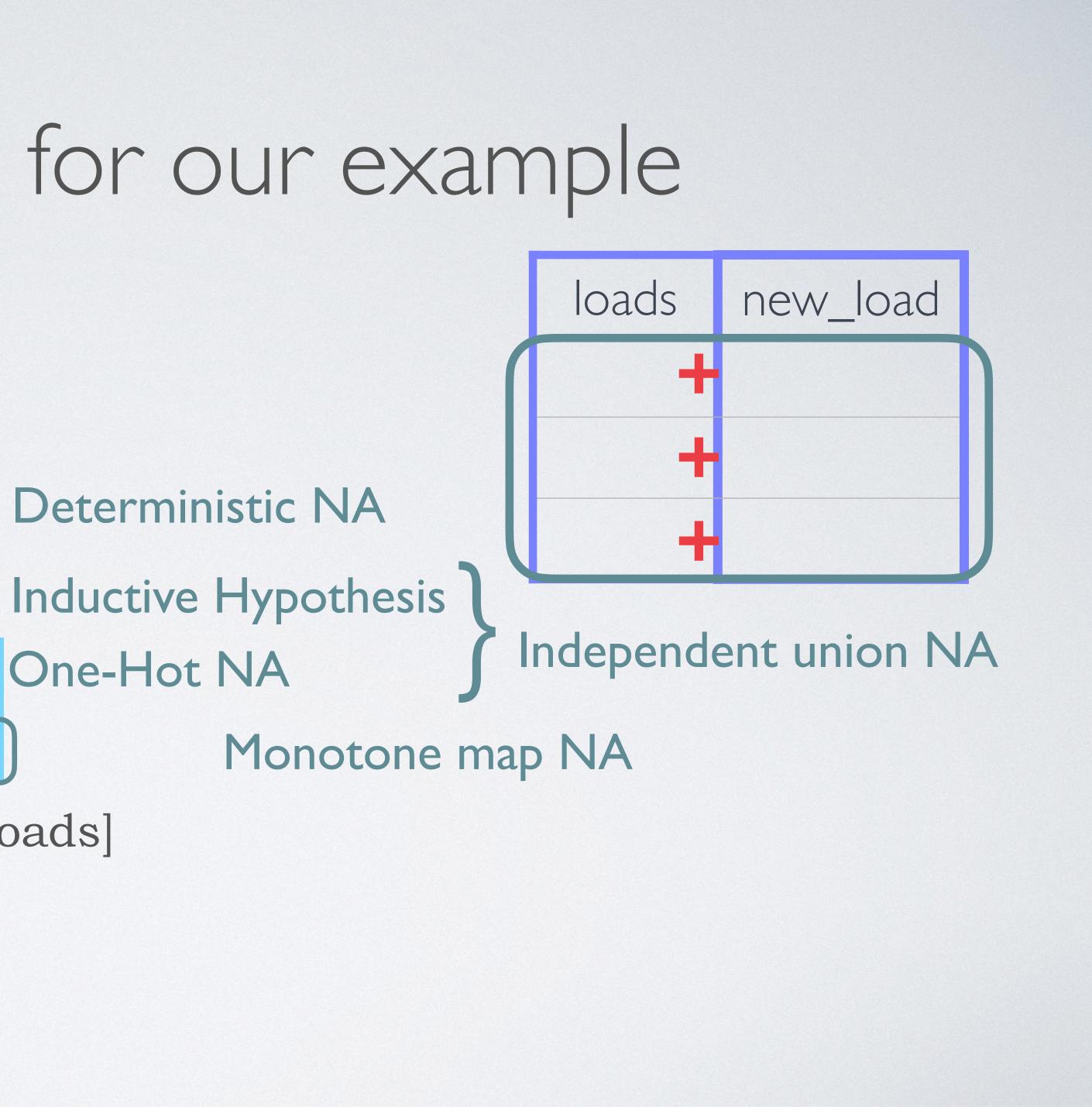


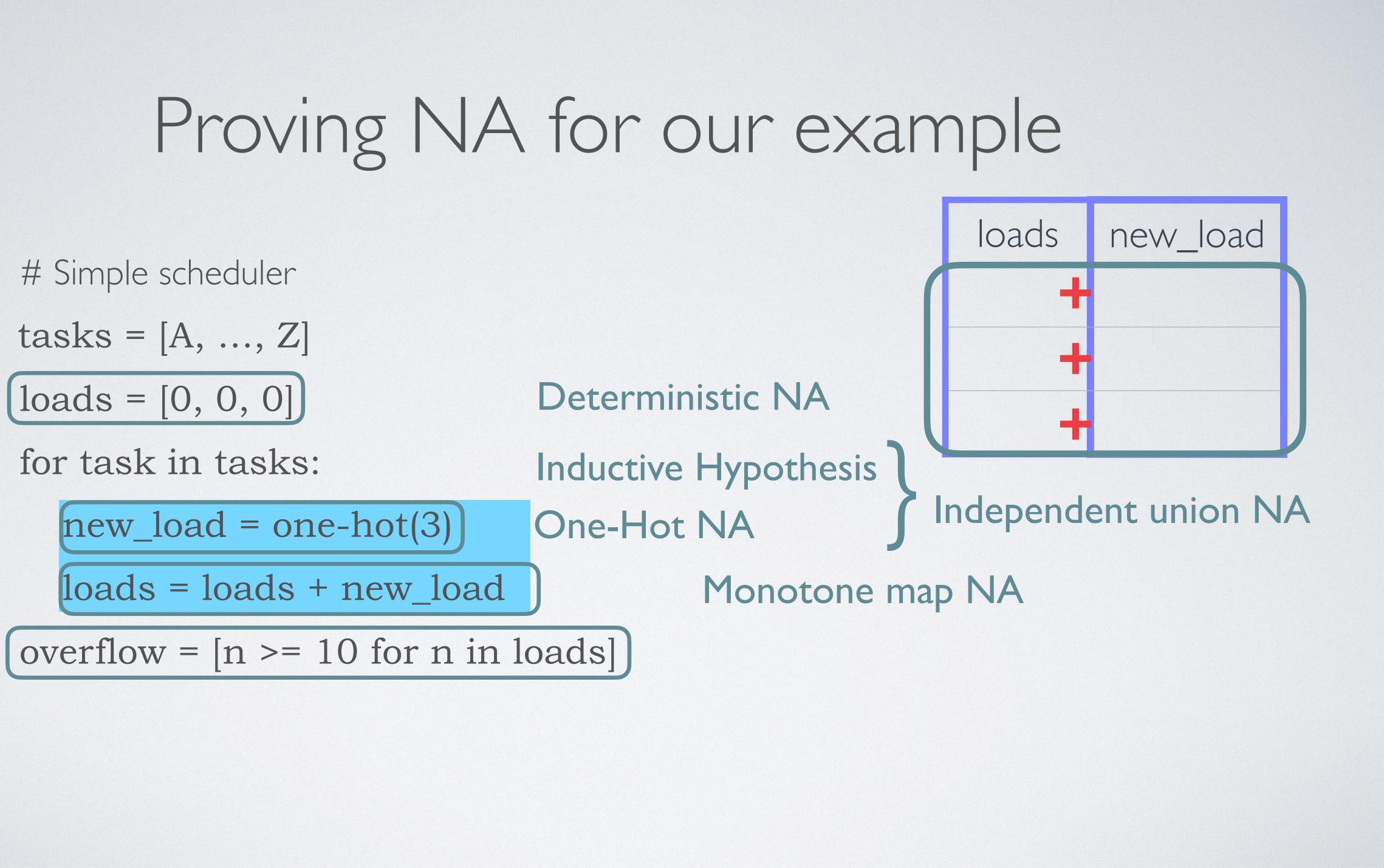


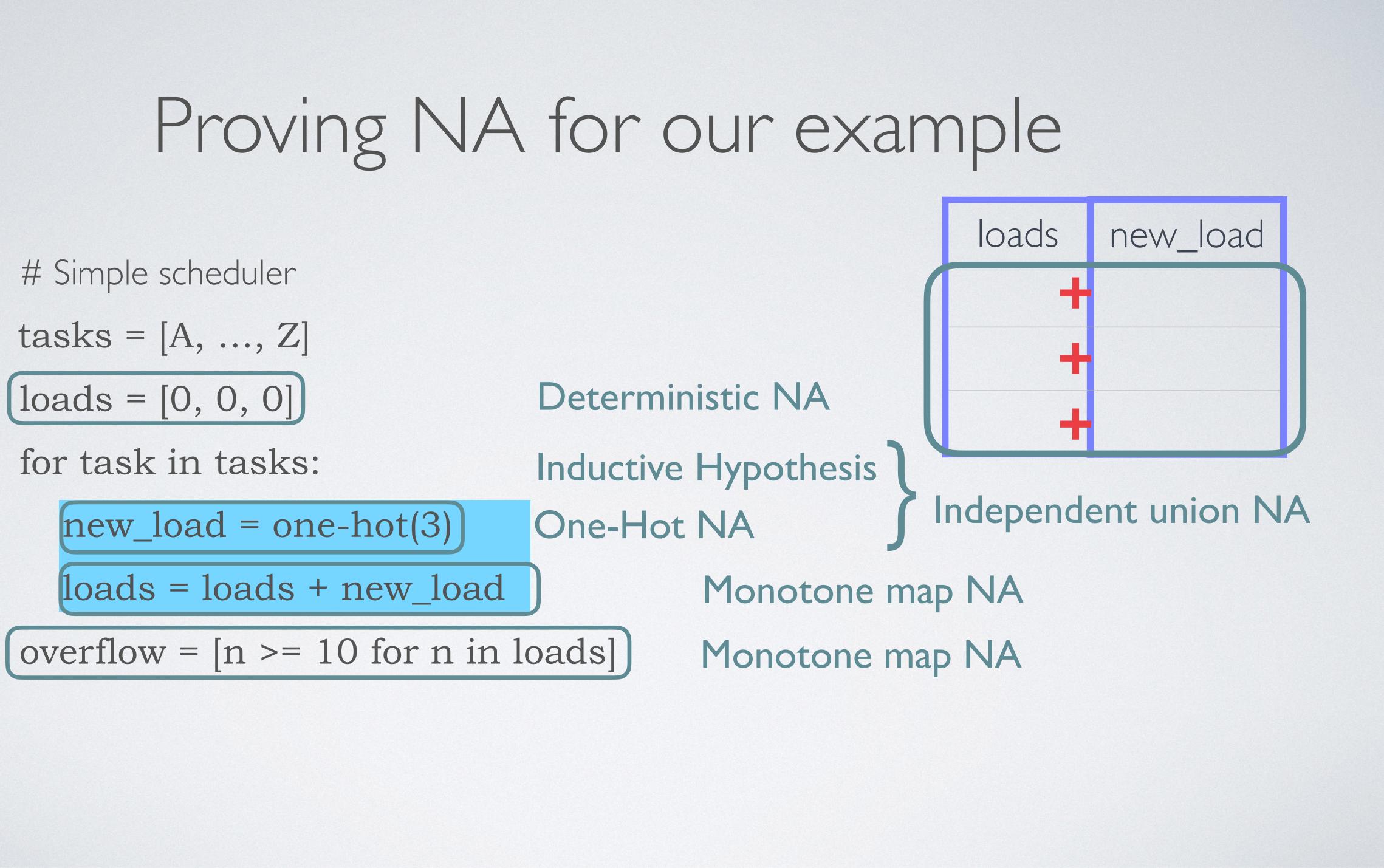


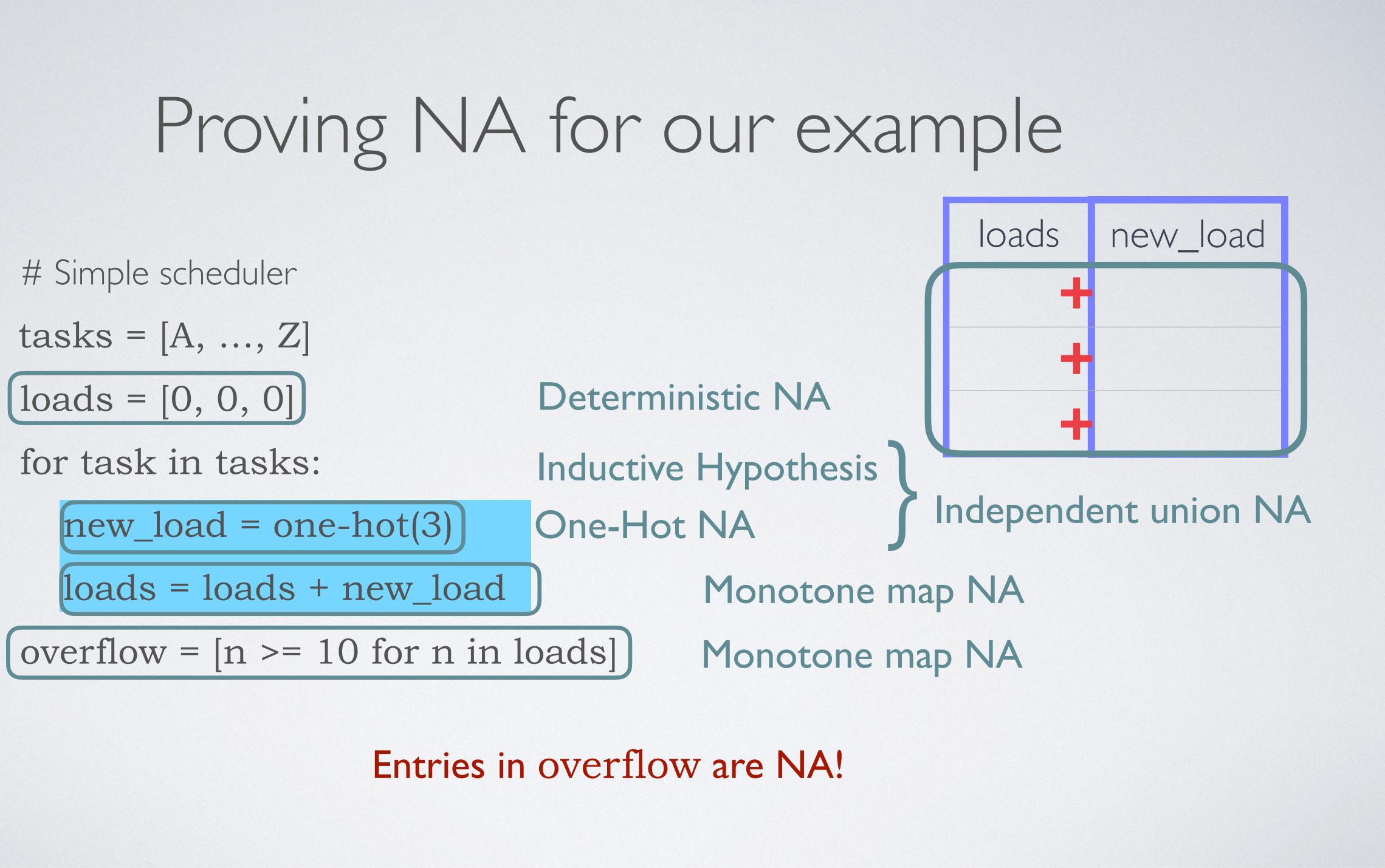












PROBABILISTIC SEPARATION LOGIC

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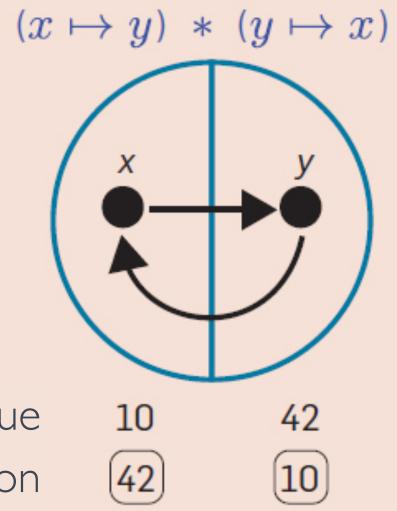
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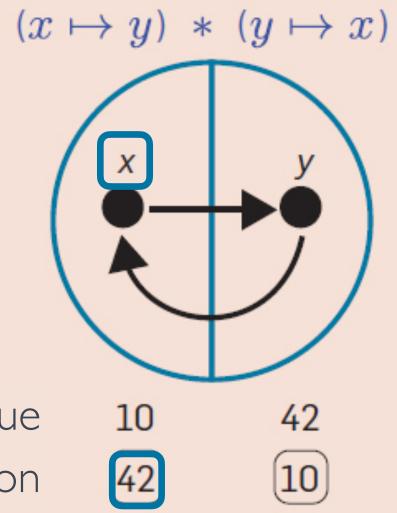


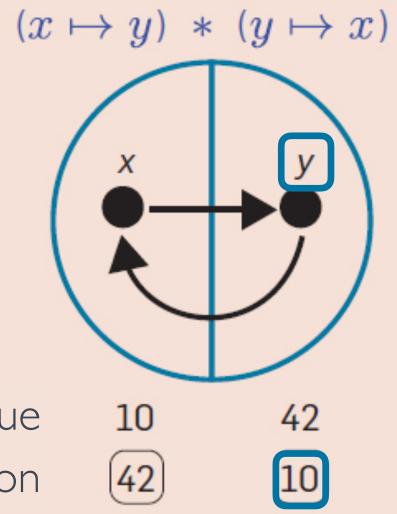
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- Outline:
 - Intuition of P * Q
 - Semantics of Bl
 - Programs and atomic propositions
 - Proof rules of program logic

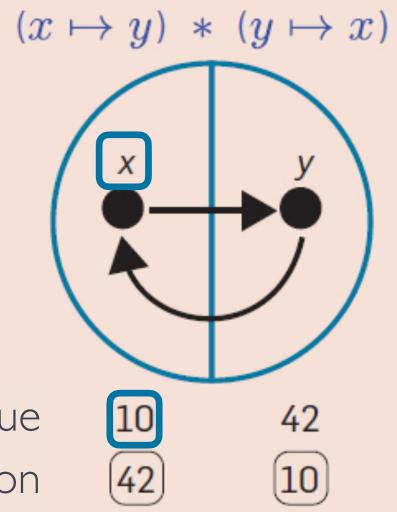
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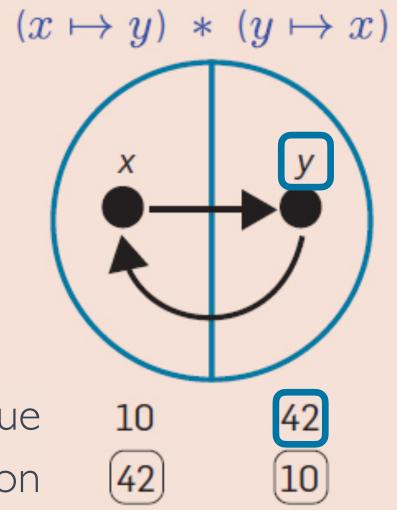


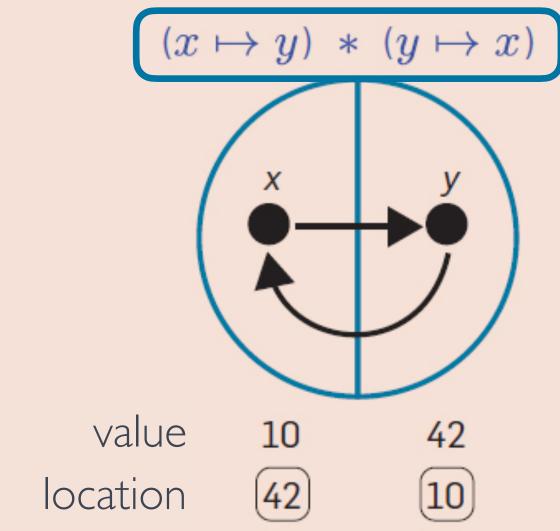




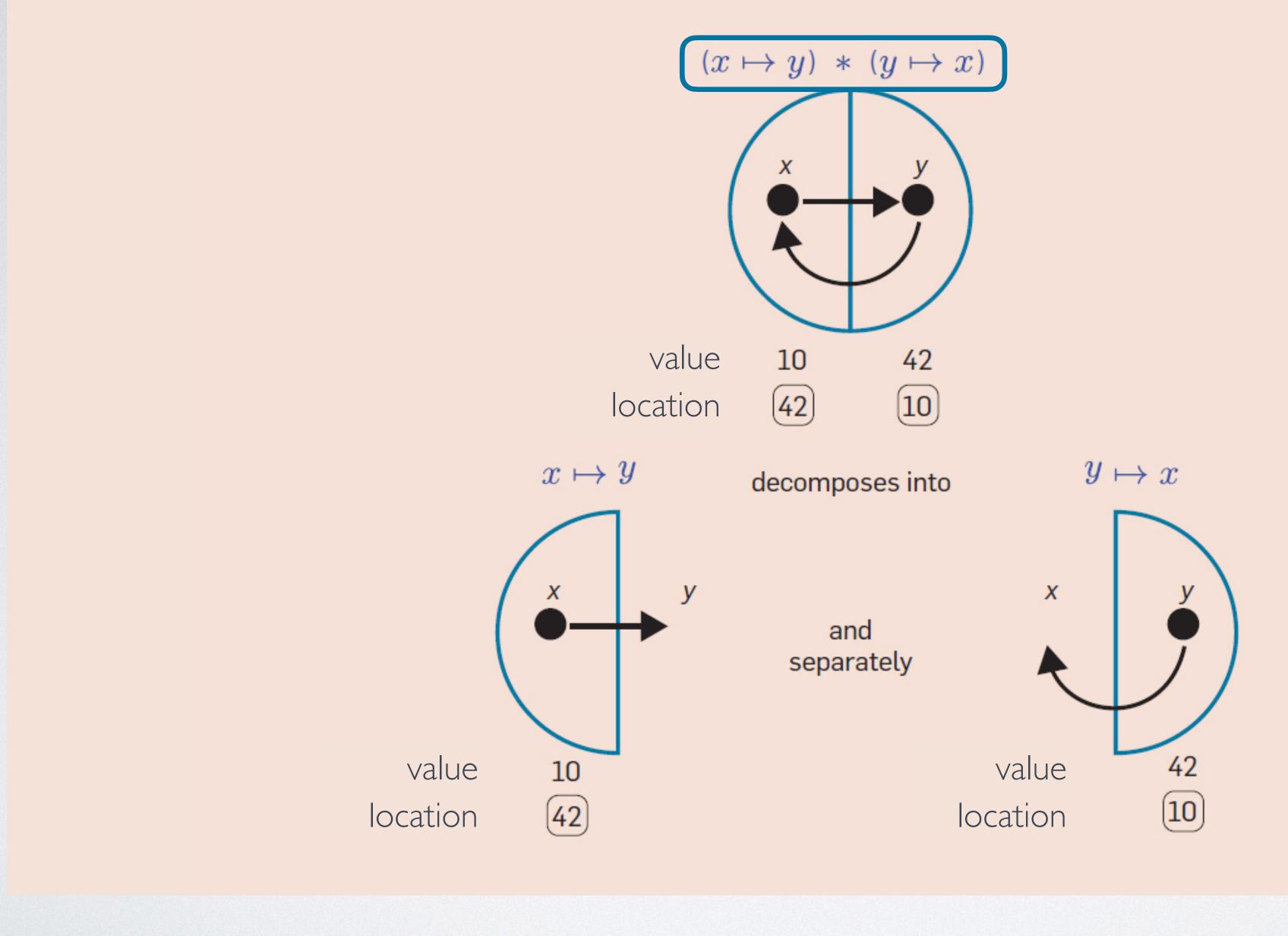


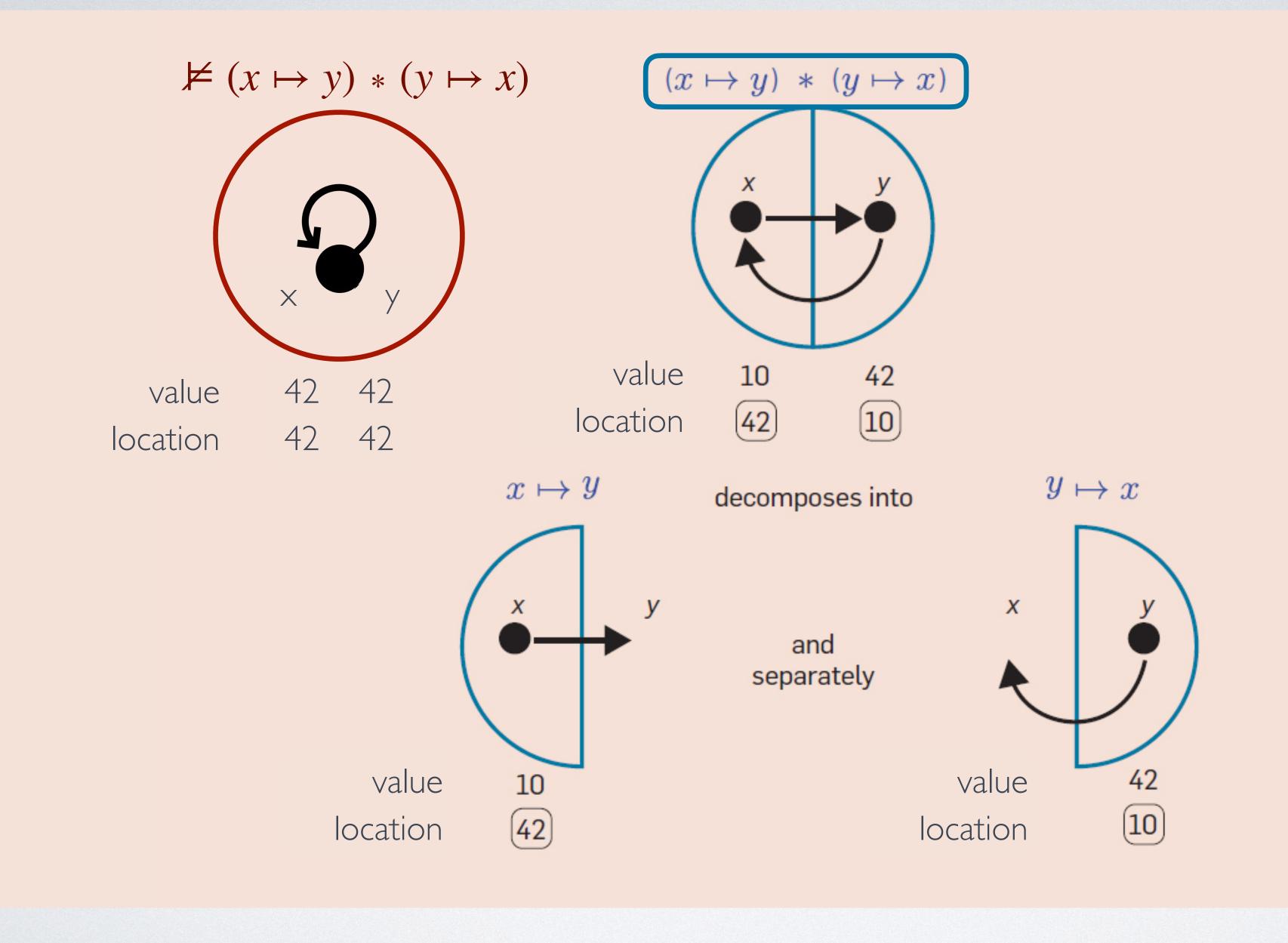


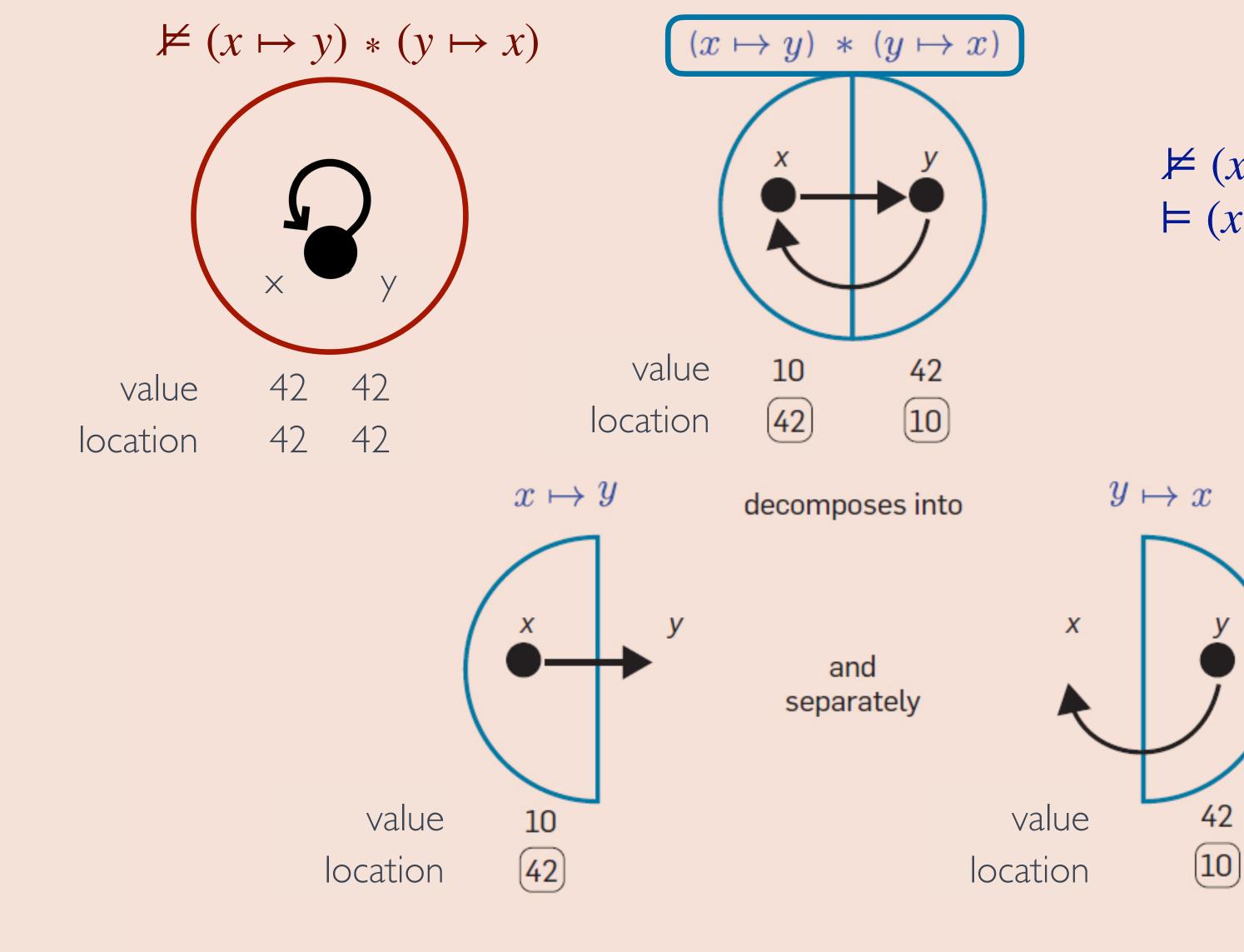












 $\nvDash (x \mapsto y) * (x \mapsto y)$ $\vDash (x \mapsto y) \land (x \mapsto y)$

- A Kripke resource monoid is a set M with
 - a partial binary operation $\circ : M \times M \rightarrow M$ that is
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 - associative: $x \circ (y \circ z) = (x \circ y) \circ z$,
 - commutative: $y \circ x = x \circ y$,
 - an identity element $e \in M$: $e \circ x = x \circ e = x$,
 - a pre-order \sqsubseteq on M:
 - transitive: if $x \sqsubseteq y$ and $y \sqsubseteq z$, then $x \sqsubseteq z$;
 - reflexive: $x \sqsubseteq x$ for any x

Distribution model

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- Let M be the set of distributions over memories,

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 - for distributions $f: X \to [0,1]$ and $g: Y \to [0,1]$, $f \circ g$ defined to be

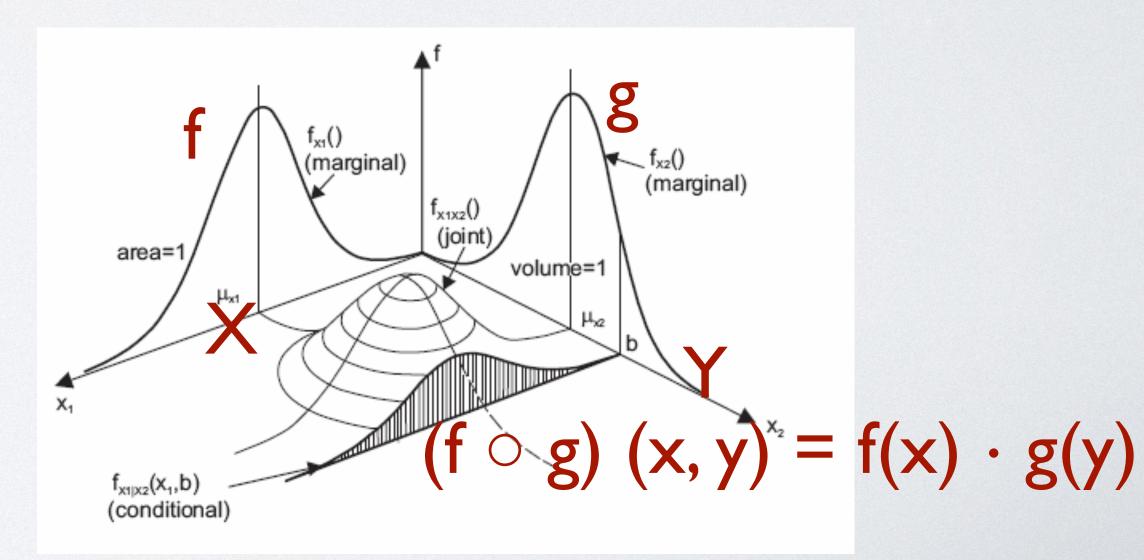
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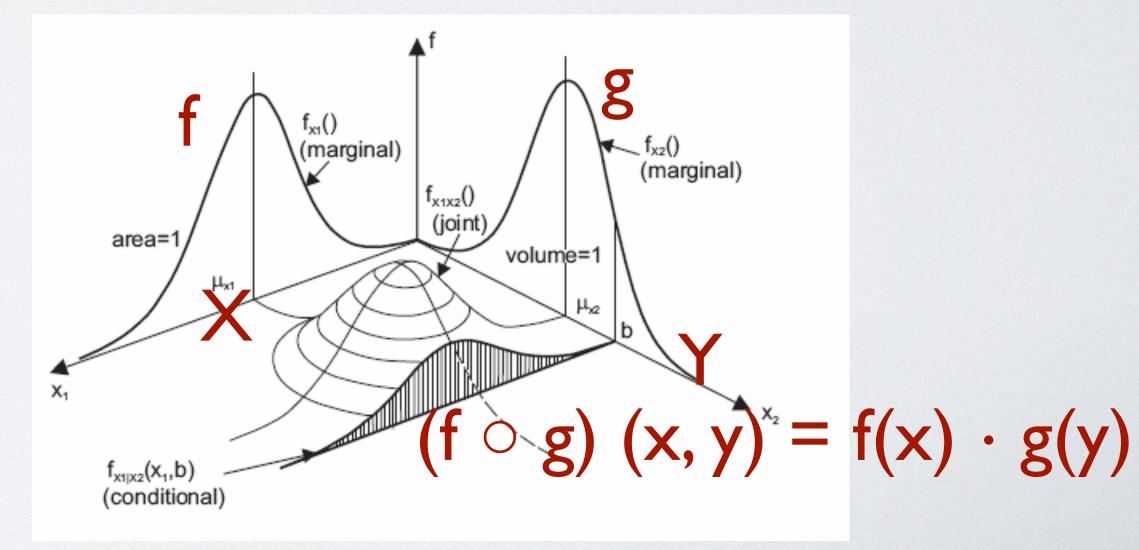


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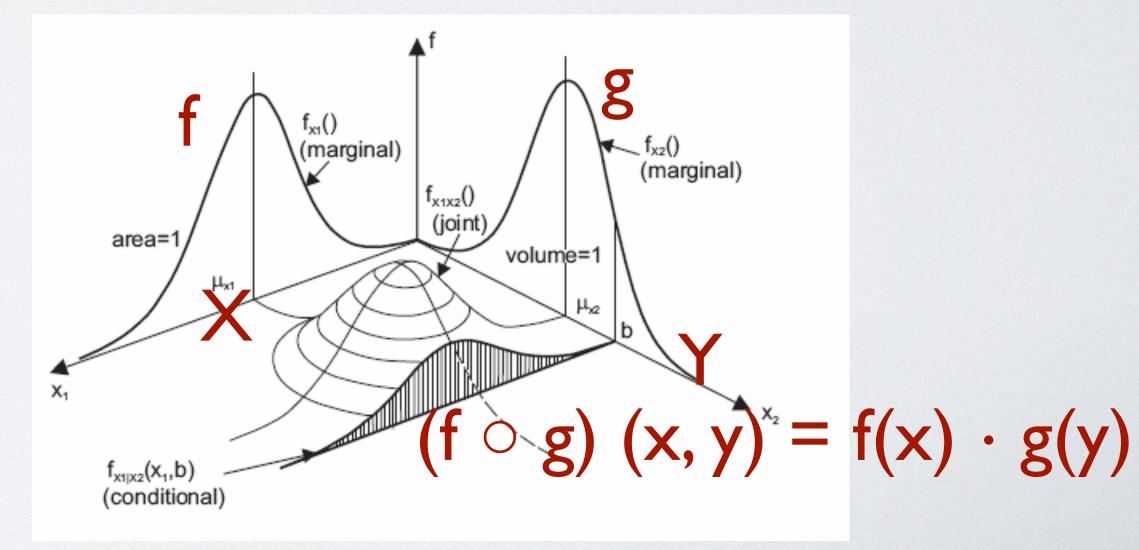


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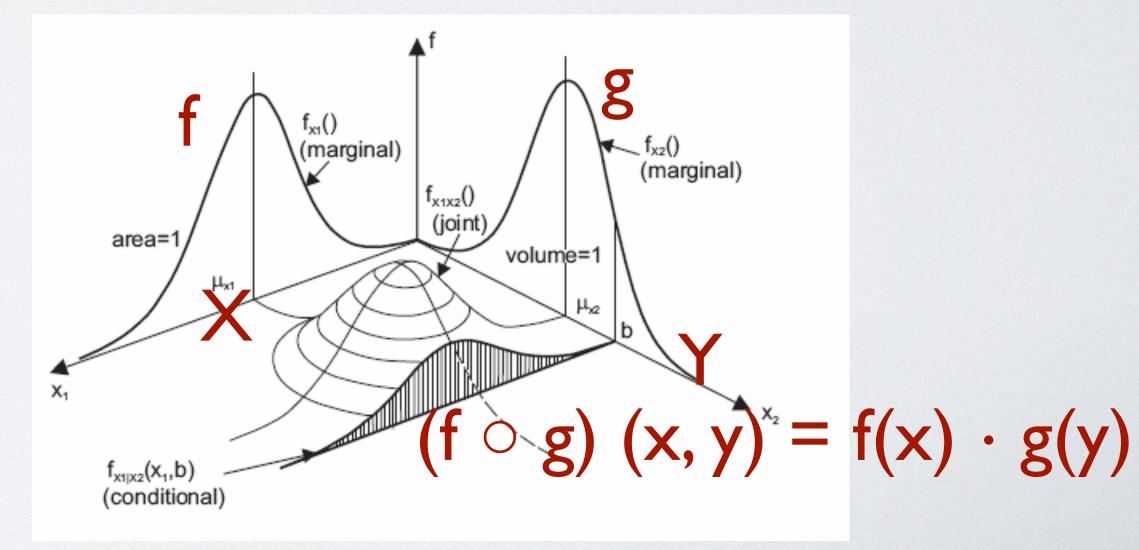
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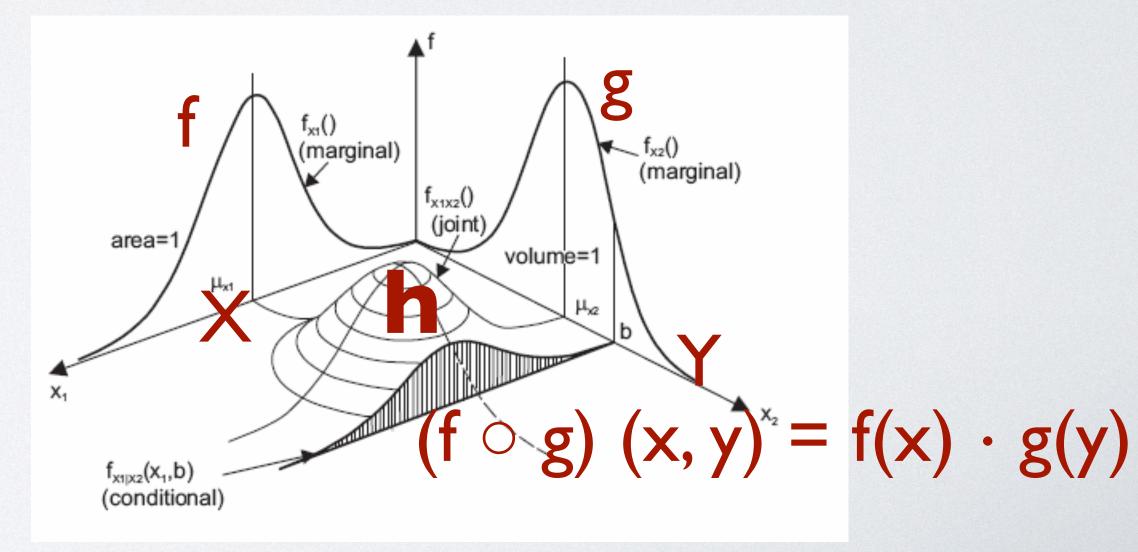
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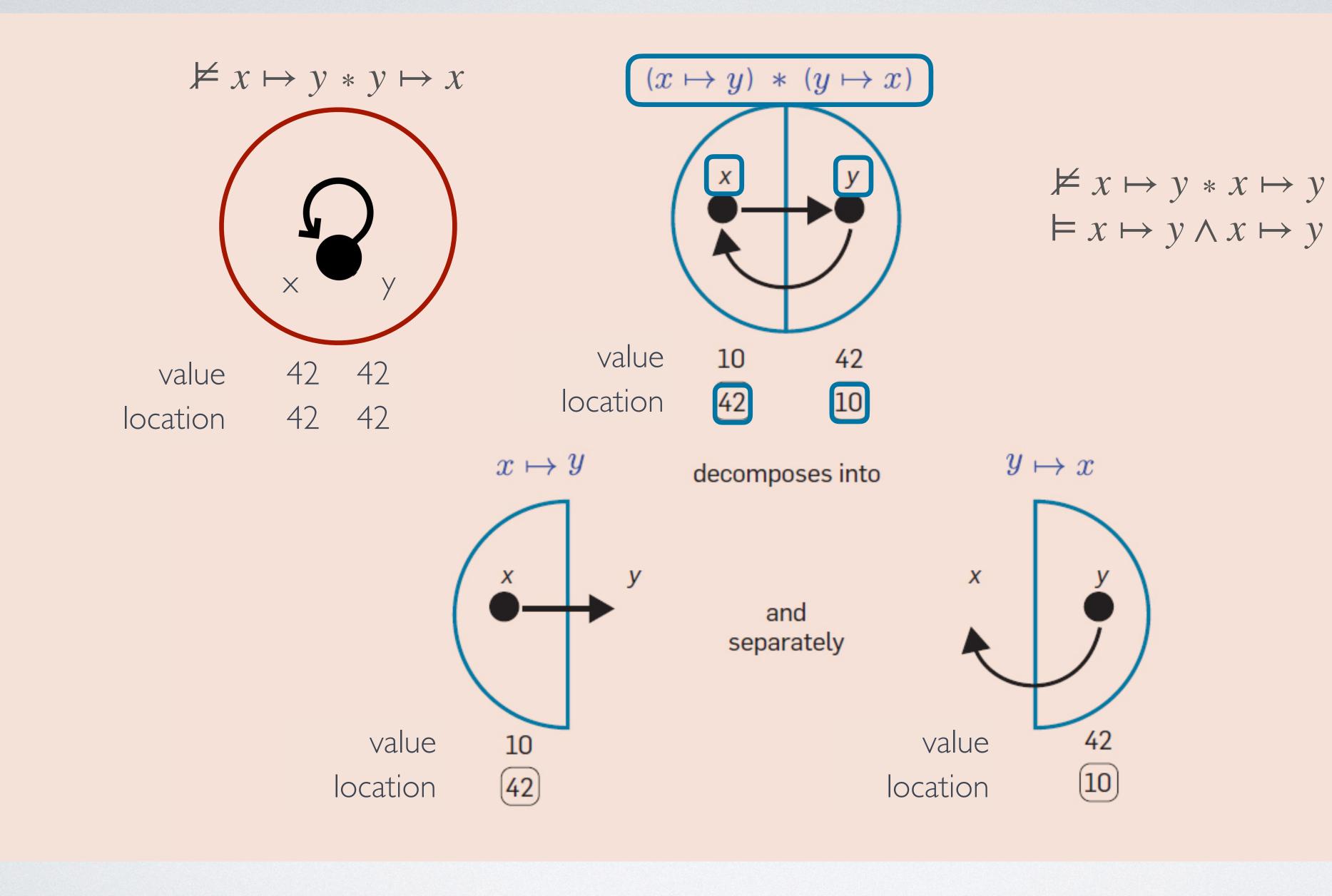
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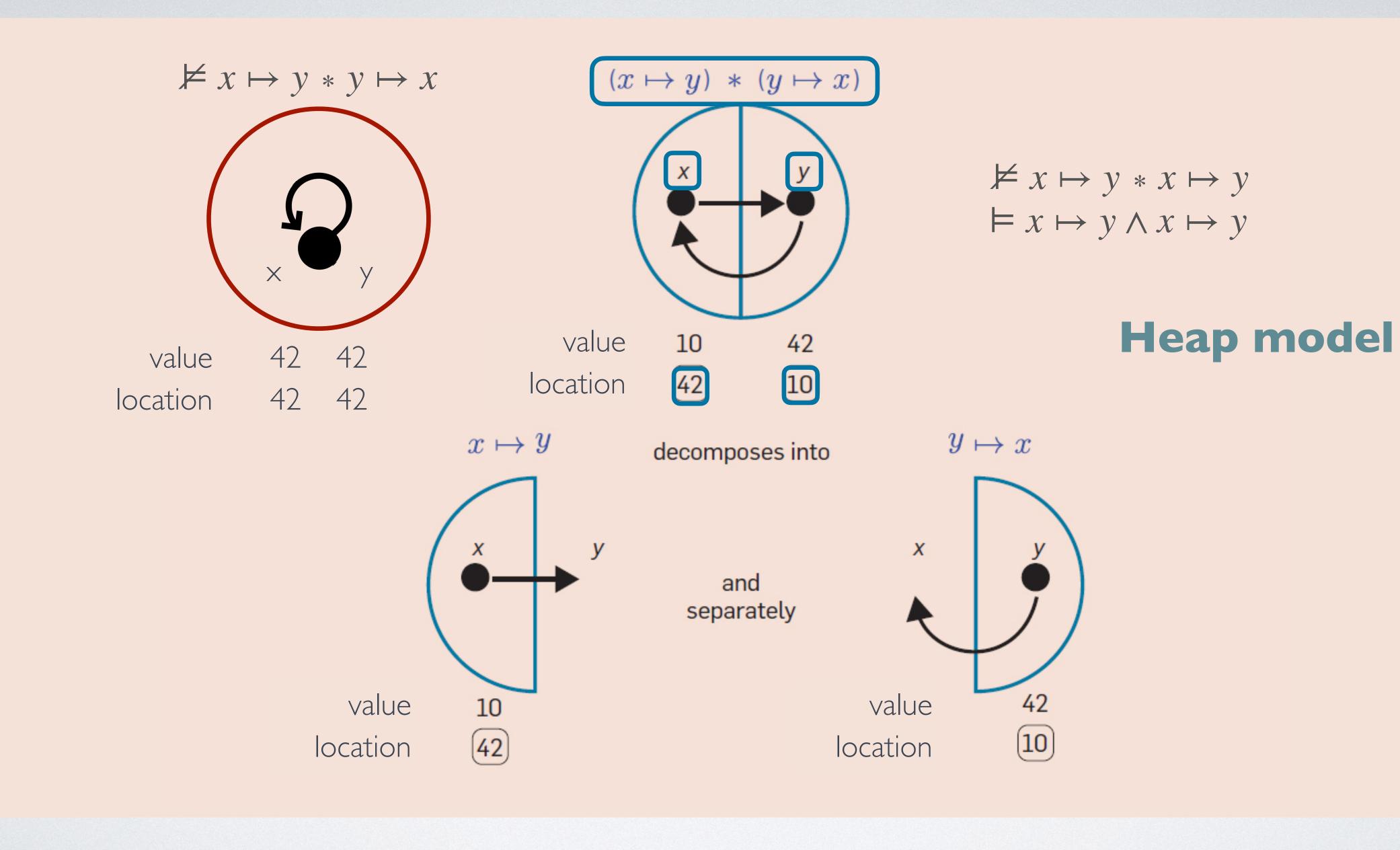
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Pumpkin Spice Latte

Probabilistic Separation Logic

credit to Joe Cutler

- - $m \models p \text{ iff } m \in \mathcal{V}(p)$

- - $m \models p \text{ iff } m \in \mathcal{V}(p)$
 - . . .

- - $m \models p \text{ iff } m \in \mathcal{V}(p)$

...

- $m \models P \land Q$ iff $m \models P$ and $m \models Q$

- - $m \models p \text{ iff } m \in \mathcal{V}(p)$

...

- $m \models P \land Q$ iff $m \models P$ and $m \models Q$

that $m_1 \models P$ and $m_2 \models Q$

- We inductively define the satisfaction relations on $m \in M$ and assertions:

- $m \models P \ast Q$ iff exist m_1, m_2 with $m_1 \circ m_2$ defined and $m_1 \circ m_2 \sqsubseteq m$ such

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- $m \models P \land Q$ iff $m \models P$ and $m \models Q$
- $m \models P * Q$ iff exist m_1, m_2 with $m_1 \circ m_2$ defined and $m_1 \circ m_2 \sqsubseteq m$ such

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P * Q

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In the independence model: -

- $m \models \langle X \rangle * \langle Y \rangle$ iff variables X, Y are independent in m

P Q P * O

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$$\mu \models e \sim e'$$

- $\mu \models \langle e \rangle$ iff $\mu \models e \sim e$

Proof Rules



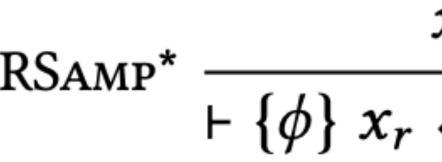
$$\operatorname{RSAMP}^* \frac{1}{\vdash \{\phi\} x_r}$$

Proof Rules

 $x_r \notin \mathrm{FV}(\phi)$ $\Leftarrow \mathbf{U}_S \left\{ \phi * \mathbf{U}_S \langle x_r \rangle \right\}$



Proof Rules



$\vdash \{\phi\} c\{\psi\}$ c does not modifies $FV(\eta)$ side conditions FRAME $\vdash \{\phi * \eta\} C\{\psi * \eta\}$

 $\operatorname{RSAMP}^* \frac{x_r \notin \operatorname{FV}(\phi)}{\vdash \{\phi\} x_r \notin \operatorname{U}_S \{\phi * \operatorname{U}_S(x_r)\}}$



A SEPARATION LOGIC FOR NEGATIVE DEPENDENCE

on assertion logic

Independence \rightarrow Negative Association

on assertion logic

Independence \rightarrow Negative Association

$\langle X_1 \rangle * \langle X_2 \rangle * \dots * \langle X_n \rangle$ asserts X_1, \dots, X_n independent in distribution model

on assertion logic

asserts X_1, \ldots, X_n NA?

Independence \rightarrow Negative Association

 $\langle X_1 \rangle * \langle X_2 \rangle * \ldots * \langle X_n \rangle$ asserts X_1, \ldots, X_n independent in distribution model Can we add another conjunction \circledast such that $\langle X_1 \rangle \circledast \langle X_2 \rangle \circledast \dots \circledast \langle X_n \rangle$

Challenge in the simplest case

Challenge in the simplest case

Say we want $\langle X_1 \rangle \circledast \langle X_2 \rangle$ asserts X_1, X_2 NA in distribution model

Challenge in the simplest case Say we want $\langle X_1 \rangle \otimes \langle X_2 \rangle$ asserts X_1, X_2 NA in distribution model Define some \oplus : M × M → M, and let $\mu \models \langle X_1 \rangle \otimes \langle X_2 \rangle$ iff exist μ_1, μ_2 with $\mu_1 \oplus \mu_2$ defined and $\mu_1 \oplus \mu_2 \sqsubseteq \mu$ such that $\mu_1 \models \langle X_1 \rangle$ and $\mu_2 \models \langle X_2 \rangle$

Challenge in the simplest case Say we want $\langle X_1 \rangle \otimes \langle X_2 \rangle$ asserts X_1, X_2 NA in distribution model **Define some** \oplus : M × M → M, and X_1, X_2 NA in μ iff exist μ_1, μ_2 with $\mu_1 \oplus \mu_2$ defined and $\mu_1 \oplus \mu_2 \sqsubseteq \mu$ such that $\mu_1 \models \langle X_1 \rangle$ and $\mu_2 \models \langle X_2 \rangle$

$$\mu_1(X_1 = 1) = \mu_2(X_2 = 1) = \frac{1}{3}$$

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$$\mu_1(X_1 = 1) = \mu_2(X_2 = 1) = \frac{1}{3}$$

 $\mu_1(X_1 = 0) = \mu_2(X_2 = 0) = \frac{2}{2}$

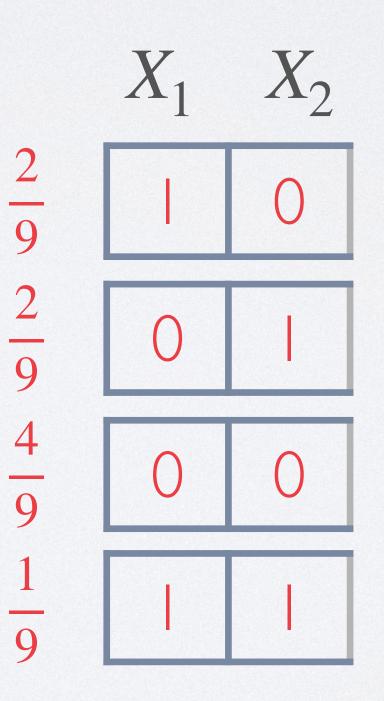
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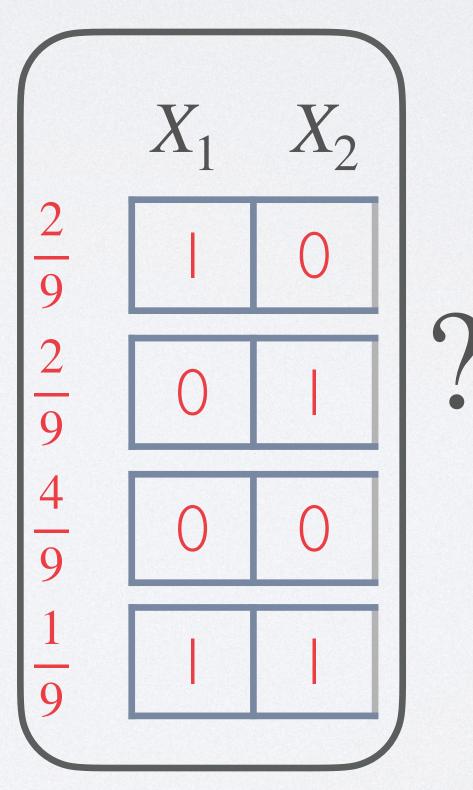
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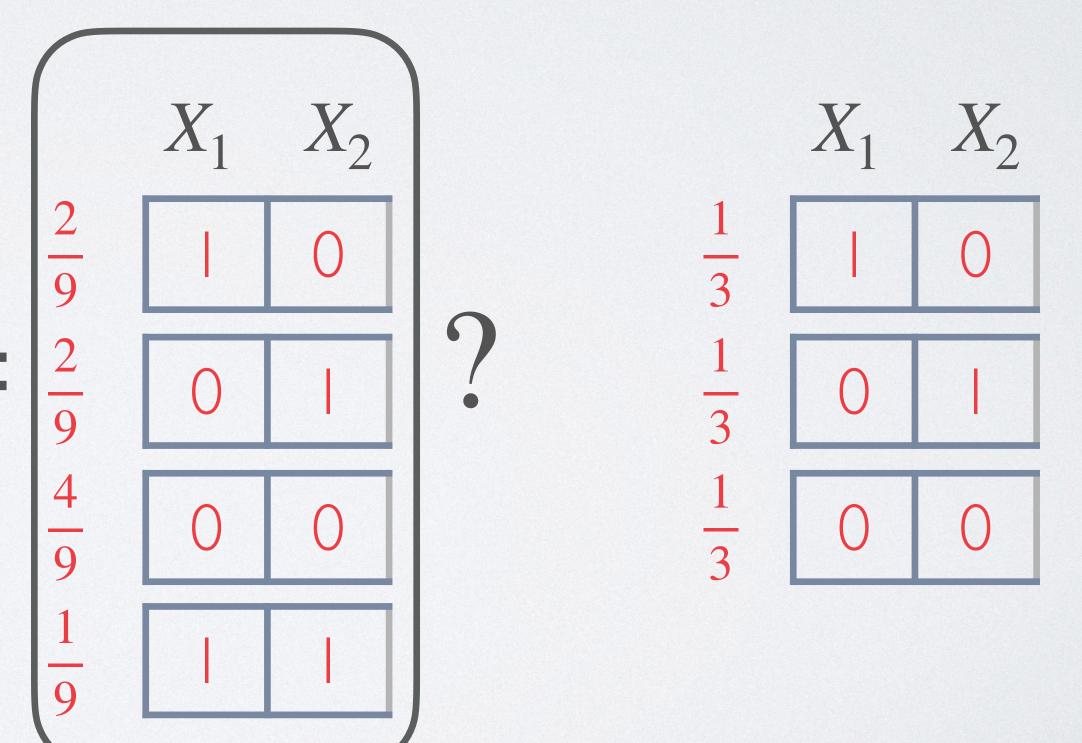
$$\mu_1(X_1 = 1) = \mu_2(X_2 = 1) = \frac{1}{3}$$
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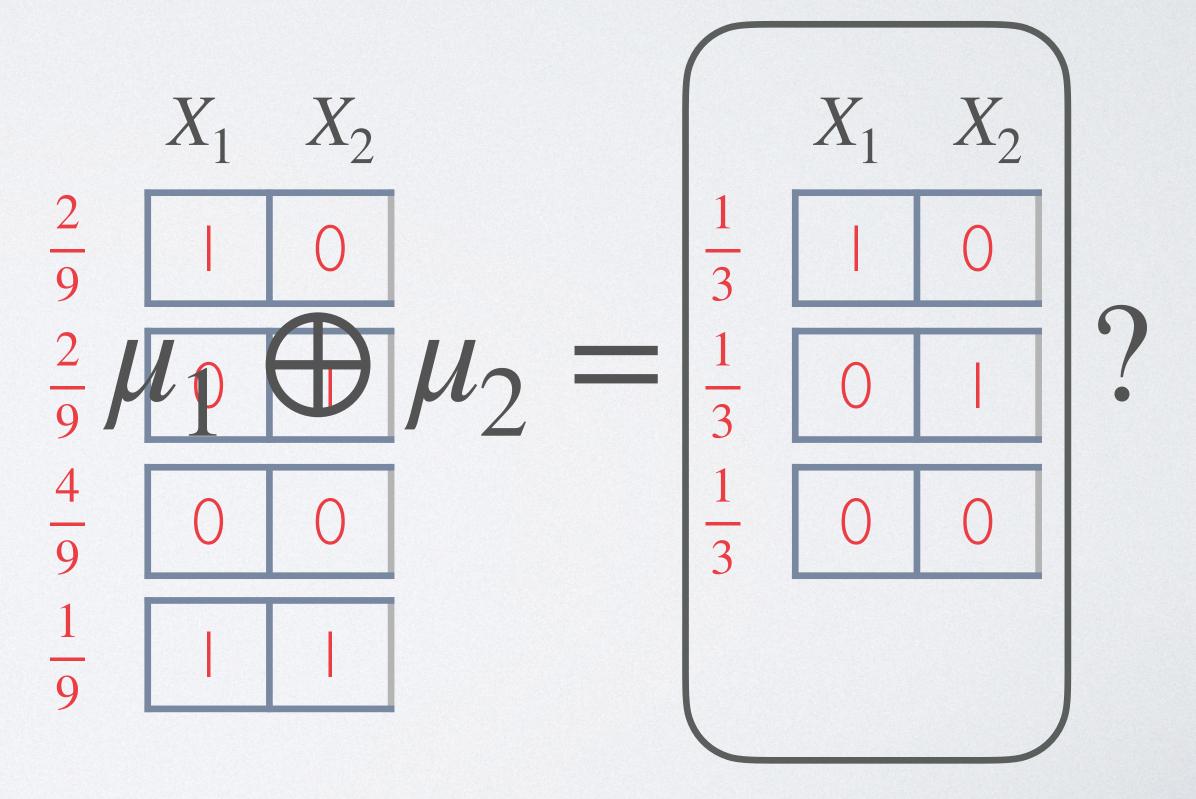
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 $\mu_1(X_1 = 0) = \mu_2(X_2)$ ____

Challenge in the simplest case **Define some** \oplus : M × M → M, and X_1, X_2 NA in μ iff exist μ_1, μ_2 with



- A Kripke resource monoid is a set M with
 - a partial binary operation $\circ : M \times M \rightarrow M$ that is
 - associative
 - commutative
 - an identity element $e \in M$
 - a pre-order ⊑ on M

- A Kripke resource monoid is a set M with
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- ABI frame [Docherty 2019] is a set M with
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Solution for the Challenge

- A BI frame [Docherty 2019] is a set M with
 - a binary operation $\circ: M \times M \to \mathscr{P}(M)$ that is
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$\mu_1 \oplus \mu_2 = \{\mu \mid \text{variables in } \mu_1, \mu_2 \text{ satisfy some sort of NA in } \mu\}$

Skipping other challenges, we have

 $\langle X_1 \rangle \circledast \langle X_2 \rangle \circledast \dots \circledast \langle X_n \rangle$ asserts X_1, X_2, \dots, X_n NA

- Deterministic variables
- Independent random variables
- Bernoulli random variables that sum to I
- Uniformly random permutations
- **Closure of Negative Association:**
- Subsets of NA variables are NA
- Union of independent NA sets is also NA
- Monotonically increasing map preserves NA

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All valid axioms!

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$P * Q \vdash P \circledast Q$

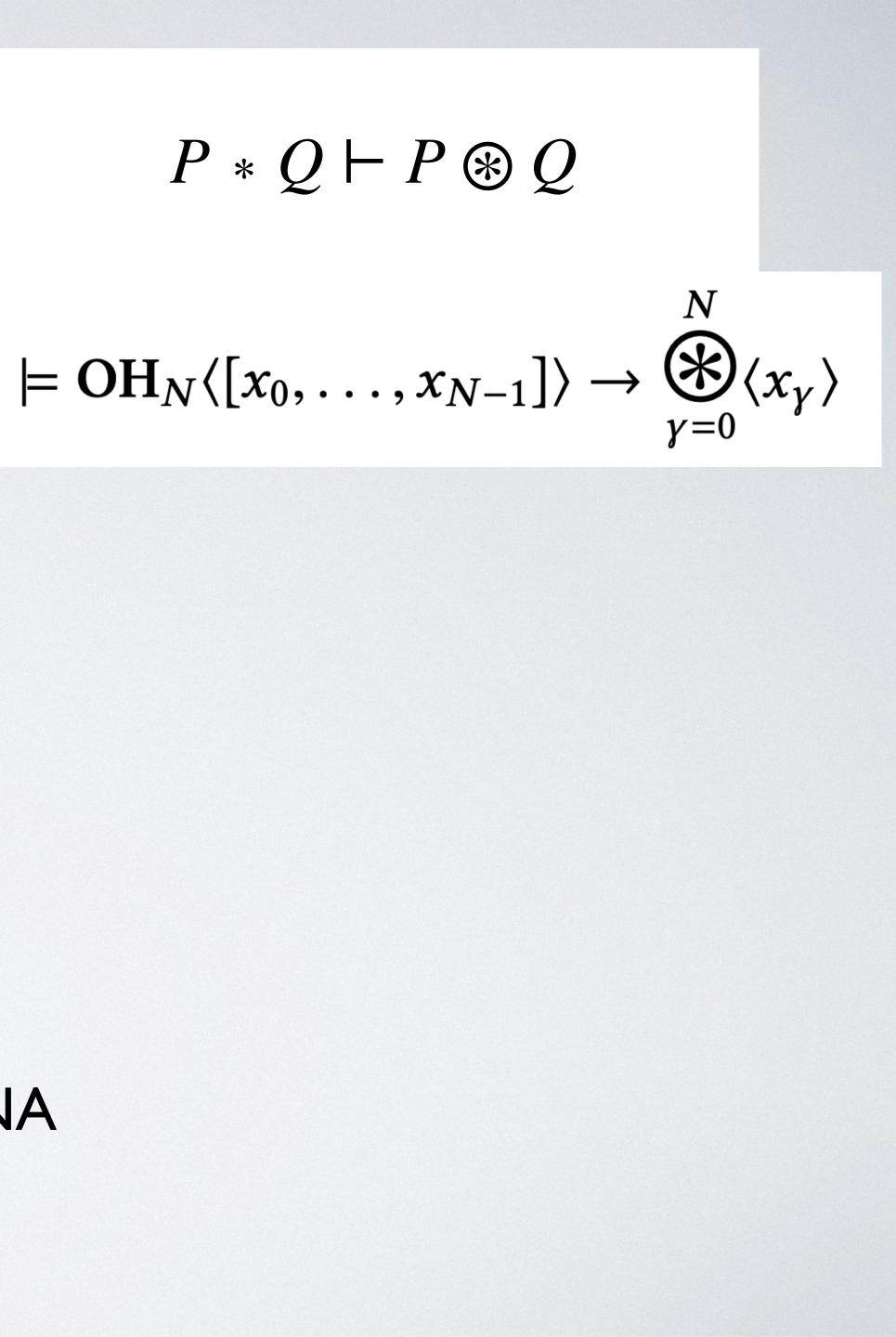


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All valid axioms!

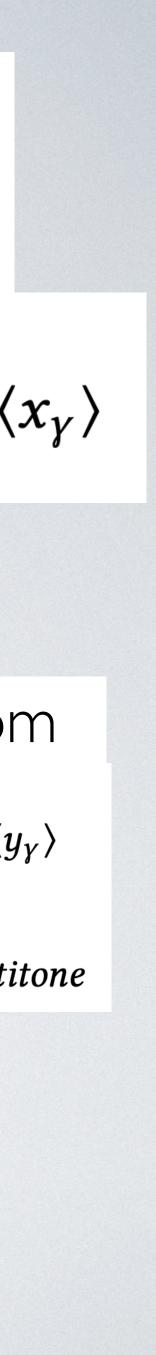
- **Closure of Negative Association**
- Subsets of NA variables are NA when f_1, \ldots, f_N all monotone or all antitone
- Union of independent NA sets is also NA
- Monotonically increasing map preserves NA

$P * Q \vdash P \circledast Q$

 $\models \operatorname{OH}_N \langle [x_0, \ldots, x_{N-1}] \rangle \to \bigotimes_{\gamma=0}^{\infty} \langle x_\gamma \rangle$

Mono-map Axiom

on:
$$\models \bigotimes_{\gamma=0}^{N} \left(\bigwedge_{\alpha=0}^{K_{\gamma}+1} \langle x_{\gamma,\alpha} \rangle \right) \land \bigwedge_{\gamma=0}^{N} y_{\gamma} = f_{\gamma} \left(x_{\gamma,0}, \dots, x_{\gamma,K_{\gamma}} \right) \to \bigotimes_{\gamma=0}^{N} \langle y_{\gamma,\alpha} \rangle$$



Independence \rightarrow Negative Association

Independence → on program logic A RSamp rule for NA?

Independence \rightarrow Negative Association

Independence \rightarrow on program logic A RSamp rule for NA?

Independence \rightarrow Negative Association

 $\operatorname{RSAMP}^* \frac{x_r \notin \operatorname{FV}(\phi)}{\vdash \{\phi\} x_r \notin \operatorname{U}_S \{\phi * \operatorname{U}_S \langle x_r \rangle\}}$

Independence \rightarrow Negative Association on program logic $\operatorname{RSAMP}^* \frac{x_r \notin \operatorname{FV}(\phi)}{\vdash \{\phi\} x_r \notin \operatorname{U}_S \{\phi * \operatorname{U}_S(x_r)\}}$ **A RSamp rule for NA?**

A frame rule for NA?

Independence \rightarrow Negative Association on program logic $\operatorname{RSAMP}^* \frac{x_r \notin \operatorname{FV}(\phi)}{\vdash \{\phi\} x_r \notin \operatorname{U}_S \{\phi * \operatorname{U}_S \langle x_r \rangle\}}$ **A RSamp rule for NA?** A frame rule for NA?

c does not modifies $FV(\eta)$ side conditions $\vdash \{\phi\}c\{\psi\}$

 $\vdash \{\phi * \eta\} C\{\psi * \eta\}$

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Independence \rightarrow Negative Association on program logic $\operatorname{RSAMP}^* \frac{x_r \notin \operatorname{FV}(\phi)}{\vdash \{\phi\} x_r \notin \operatorname{U}_S \{\phi * \operatorname{U}_S(x_r)\}}$ **A RSamp rule for NA?** NA preserved under monotone maps A frame rule for NA? c is a monotonically increasing map from $dom(\phi)$ to $dom(\psi)$ c does not modifies $FV(\eta)$ $\vdash \{\phi\}c\{\psi\}$ side conditions

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A frame rule for NA

c does not modifies $FV(\eta)$ side conditions $\vdash \{\phi\}c\{\psi\}$

Independence \rightarrow Negative Association

 $\vdash \{\phi \circledast \eta\} c\{\psi \circledast \eta\}$

A frame rule for NA $\langle y \rangle$ obtained from a monotonically increasing map on $dom(\phi)$ c does not modifies $FV(\eta)$ $\vdash \{\phi\} c\{\langle y \rangle\}$ side conditions

Independence \rightarrow Negative Association

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A frame rule for NA $\langle y \rangle$ obtained from a monotonically increasing map on $dom(\phi)$ c does not modifies $FV(\eta)$ $\vdash \{\phi\} c\{\langle y \rangle\}$ side conditions NA-FRAME

Independence \rightarrow Negative Association

 $\vdash \{\phi \circledast \eta\} c\{\langle y \rangle \circledast \eta\}$



APPLICATIONS

to the motivating example

tasks = [A, ..., Z]loads = [0, 0, 0]

for task in tasks: new_load = one-hot(3) loads = loads + new_load

overflow = $[n \ge 10 \text{ for } n \text{ in loads}]$

tasks = [A, ..., Z] loads = [0, 0, 0] i = 0

while i < |tasks|: i = i + 1 new_load = one-hot(3) loads = loads + new_load

overflow = $[n \ge 10 \text{ for } n \text{ in loads}]$

tasks = [A, ..., Z]loads = [0, 0, 0]i = 0 $\{ \bigotimes_{i \in \{0,1,2\}} | oads[i] \}$ while i < |tasks|: i = i + 1 $new_load = one-hot(3)$ loads = loads + new_load $\{ \circledast_{i \in \{0,1,2\}} | oads[i] \}$ overflow = $[n \ge 10 \text{ for } n \text{ in loads}]$

In our informal proof

tasks = [A, ..., Z] loads = [0, 0, 0] i = 0

while i < |tasks|: i = i + 1 new_load = one-hot(3) loads = loads + new_load

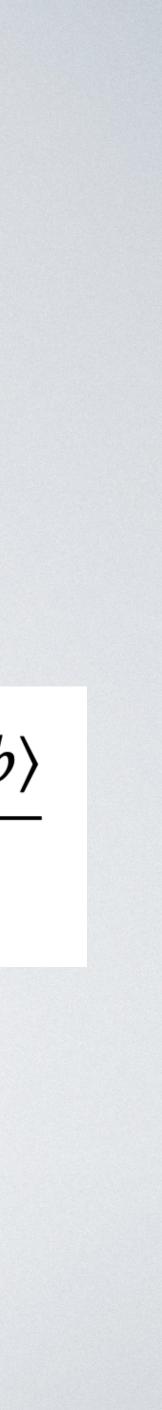
overflow = $[n \ge 10 \text{ for } n \text{ in loads}]$

LOOP $\frac{\vdash \{\phi \land b \sim tt\} c \{\phi\}}{\vdash \{\phi\} \text{ while } b \text{ do } c \{\phi \land b \sim ff\}}$



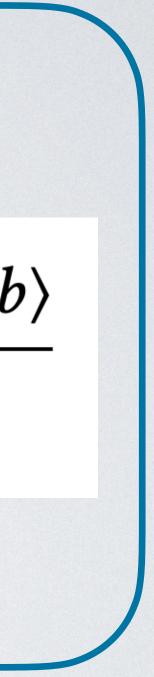
tasks = [A, ..., Z] loads = [0, 0, 0]i = 0 $\{ \bigotimes_{i \in \{0,1,2\}} | oads[i] \land Detm[i] \land Detm[task] \}$ while i < |tasks|: i = i + 1 $new_load = one-hot(3)$ loads = loads + new_load $\{ \circledast_{i \in \{0,1,2\}} | oads[i] \land Detm[i] \land Detm[task] \land (i \ge | task |) \}$ overflow = $[n \ge 10 \text{ for } n \text{ in loads}]$

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$$\begin{array}{l} \text{.OOP} & \vdash \{\phi \land b \sim tt\} \ c \ \{\phi\} & \models \phi \to \text{Detm}\langle b \\ & \vdash \{\phi\} \text{ while } b \text{ do } c \ \{\phi \land b \sim ff\} \end{array} \end{array}$$



i = i + 1

$new_load = one-hot(3)$

loads = loads + new_load

 $\{ \circledast_{i \in \{0,1,2\}} | oads[i] \land Detm[i] \land Detm[task] \land (i \ge | task |) \}$

LOOP $\frac{\vdash \{\phi \land b \sim tt\} c \{\phi\}}{\vdash \{\phi\} \text{ while } b \text{ do } c \{\phi \land b \sim ff\}}$



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DAssn $\vdash \{\psi[e_d/x_d]\} x_d \leftarrow e_d \{\psi\}$



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new_load = one-hot(3)

loads = loads + new_load

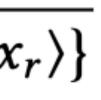
$\{ \circledast_{i \in \{0,1,2\}} | \text{oads}[i] \land \text{Detm}[i] \land \text{Detm}[\text{task}] \land (i < |\text{task}| + 1) \}$

$new_load = one-hot(3)$

loads = loads + new_load

$$\operatorname{RSAMP}^{*} \frac{x_{r} \notin \operatorname{FV}(\phi)}{\vdash \{\phi\} x_{r} \notin \operatorname{U}_{S} \{\phi * \operatorname{U}_{S}(x)\}}$$





$\{ \circledast_{i \in \{0,1,2\}} | oads[i] \land Detm[i] \land Detm[task] \land (i < |task| + 1) \}$

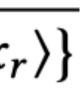
$new_load = one-hot(3)$

 $\{(\circledast_{i\in\{0,1,2\}} | oads[i] * OH_3[new_loads]) \land \dots\}$

loads = loads + new_load

 $\{ \bigotimes_{i \in \{0,1,2\}} | oads[i] \land Detm[i] \land Detm[task] \}$

 $\operatorname{RSAMP}^{*} \frac{x_r \notin \operatorname{FV}(\phi)}{\vdash \{\phi\} x_r \notin \operatorname{U}_S \{\phi * \operatorname{U}_S(x_r)\}}$

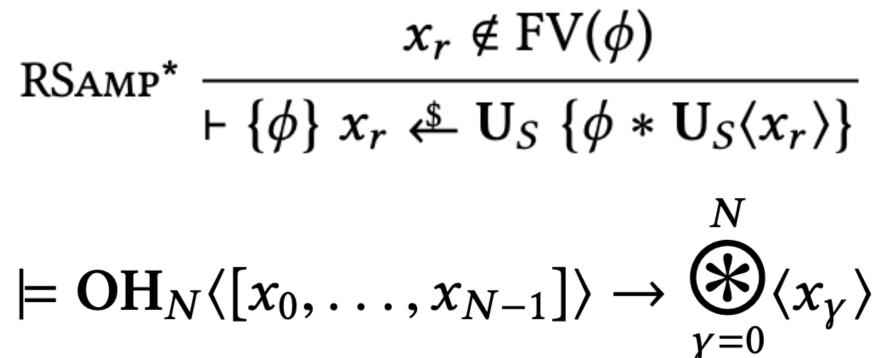


$\{ \bigotimes_{i \in \{0,1,2\}} | oads[i] \land Detm[i] \land Detm[task] \land (i < | task | + 1) \}$

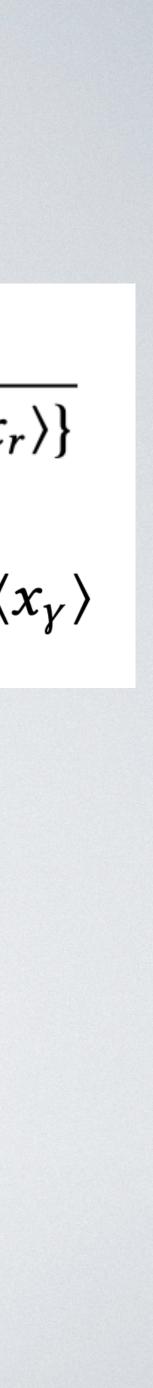
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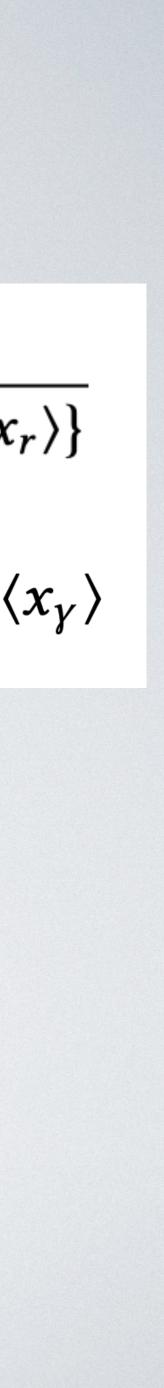




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loads = loads + new_load

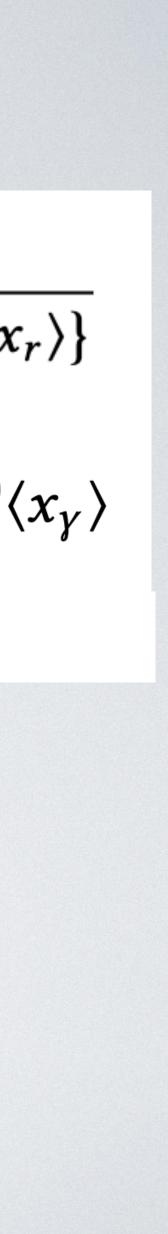
$$\operatorname{RSAMP}^{*} \frac{x_{r} \notin \operatorname{FV}(\phi)}{\vdash \{\phi\} x_{r} \notin \operatorname{U}_{S} \{\phi * \operatorname{U}_{S} \langle x \rangle\}}$$
$$\models \operatorname{OH}_{N} \langle [x_{0}, \dots, x_{N-1}] \rangle \to \bigotimes_{\nu=0}^{N} \langle x_{0} \rangle$$



 $\{ \bigotimes_{i \in \{0,1,2\}} | oads[i] \land Detm[i] \land Detm[task] \land (i < |task| + 1) \}$ $new_load = one-hot(3)$ {($\circledast_{i \in \{0,1,2\}}$ loads[i] * **OH**₃[new_loads]) $\land \dots$ } $\{(\circledast_{i \in \{0,1,2\}} | \mathsf{oads}[i] * \circledast_{i \in \{0,1,2\}} \mathsf{new}_{\mathsf{load}}[i]) \land \dots\}$

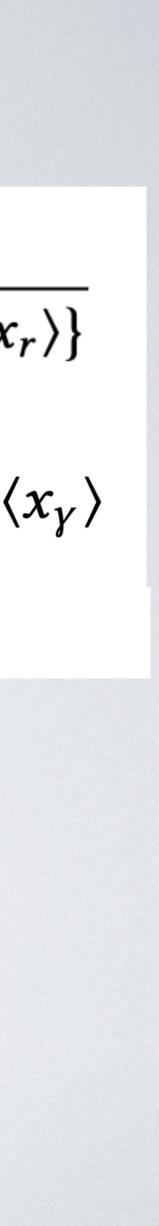
loads = loads + new_load

$$\operatorname{RSAMP}^{*} \frac{x_{r} \notin \operatorname{FV}(\phi)}{\vdash \{\phi\} x_{r} \ll \operatorname{U}_{S} \{\phi * \operatorname{U}_{S} \langle x \rangle\}}$$
$$\models \operatorname{OH}_{N} \langle [x_{0}, \dots, x_{N-1}] \rangle \rightarrow \bigotimes_{\gamma=0}^{N} \langle \varphi \rangle$$
$$P * Q \vdash P \circledast Q$$



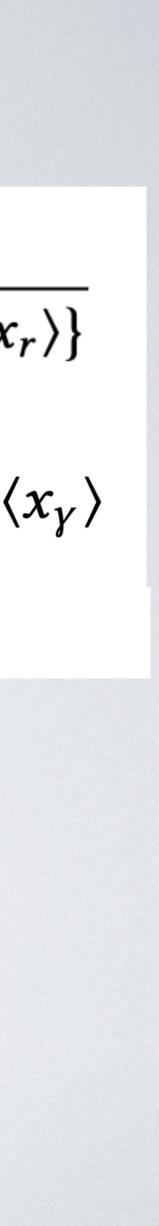
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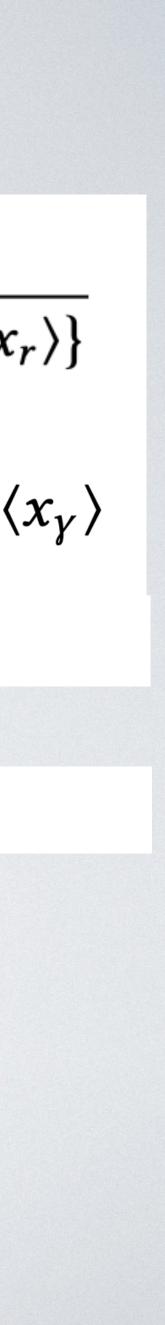
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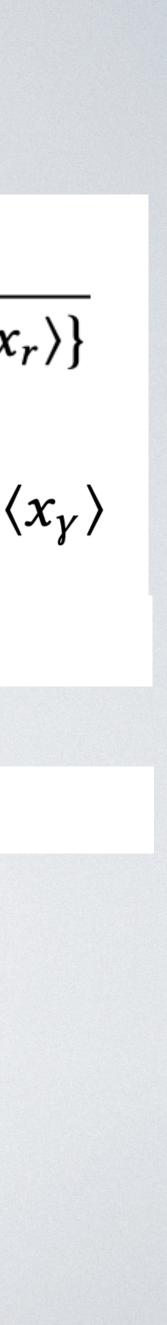


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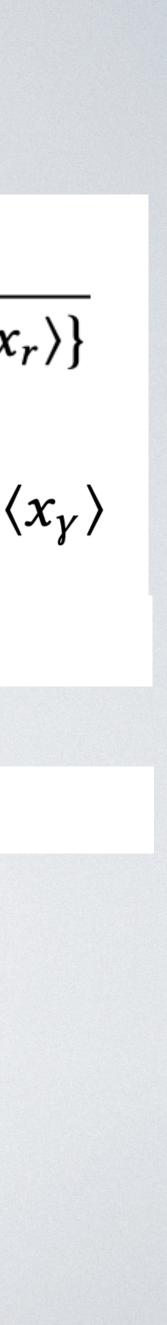
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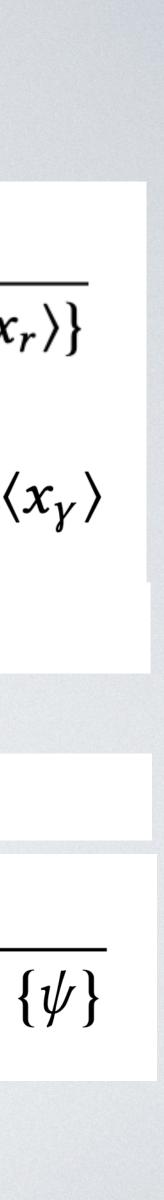
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Mono-map Axiom

DAssn $\vdash \{\psi[e_d/x_d]\} \ x_d \leftarrow e_d \ \{\psi\}$



tasks = [A, ..., Z] loads = [0, 0, 0]i = 0 $\{ \bigotimes_{i \in \{0,1,2\}} | oads[i] \land Detm[i] \land Detm[task] \}$ while i < |tasks|: i = i + 1 $\{ \circledast_{i \in \{0,1,2\}} | oads[i] \land Detm[i] \land Detm[task] \land (i < |task| + 1) \}$ $new_load = one-hot(3)$ loads = loads + new_load $\{ \bigotimes_{i \in \{0,1,2\}} | oads[i] \land Detm[i] \land Detm[task] \}$ $\{ \bigotimes_{i \in \{0,1,2\}} | oads[i] \land Detm[i] \land Detm[task] \land (i \ge | task |) \}$ overflow = $[n \ge 10 \text{ for } n \text{ in loads}]$

Scoping back ...

tasks = [A, ..., Z]loads = [0, 0, 0]i = 0 $\{ \bigotimes_{i \in \{0,1,2\}} | oads[i] \land Detm[i] \land Detm[task] \}$ while i < |tasks|: i = i + 1 $\{ \circledast_{i \in \{0,1,2\}} | oads[i] \land Detm[i] \land Detm[task] \land (i < |task| + 1) \}$ $new_load = one-hot(3)$ loads = loads + new_load $\{ \bigotimes_{i \in \{0,1,2\}} | oads[i] \land Detm[i] \land Detm[task] \}$ $\{ \bigotimes_{i \in \{0,1,2\}} | oads[i] \land Detm[i] \land Detm[task] \land (i \ge | task |) \}$ overflow = $[n \ge 10 \text{ for } n \text{ in loads}]$

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Scoping back ...

- M-BI logic: a sound and complete extension of BI that supports ordered separating conjunctions

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- Details of the NA-Frame rule
- Applications to various probabilistic data structure
 - Bloom filter

 - Permutation Hashing [Ding and König 2011] - Fully-dynamic dictionary [Bercea and Even 2019]
 - Repeated balls-into-bins [Becchetti et al. 2019]

A SEPARATION LOGIC FOR NEGATIVE DEPENDENCE

Jialu Bao at PLDG, Oct. 6, 2021 Joint work with Marco Gaboardi, Justin Hsu, Joseph Tassarotti